

Rare Event Simulations

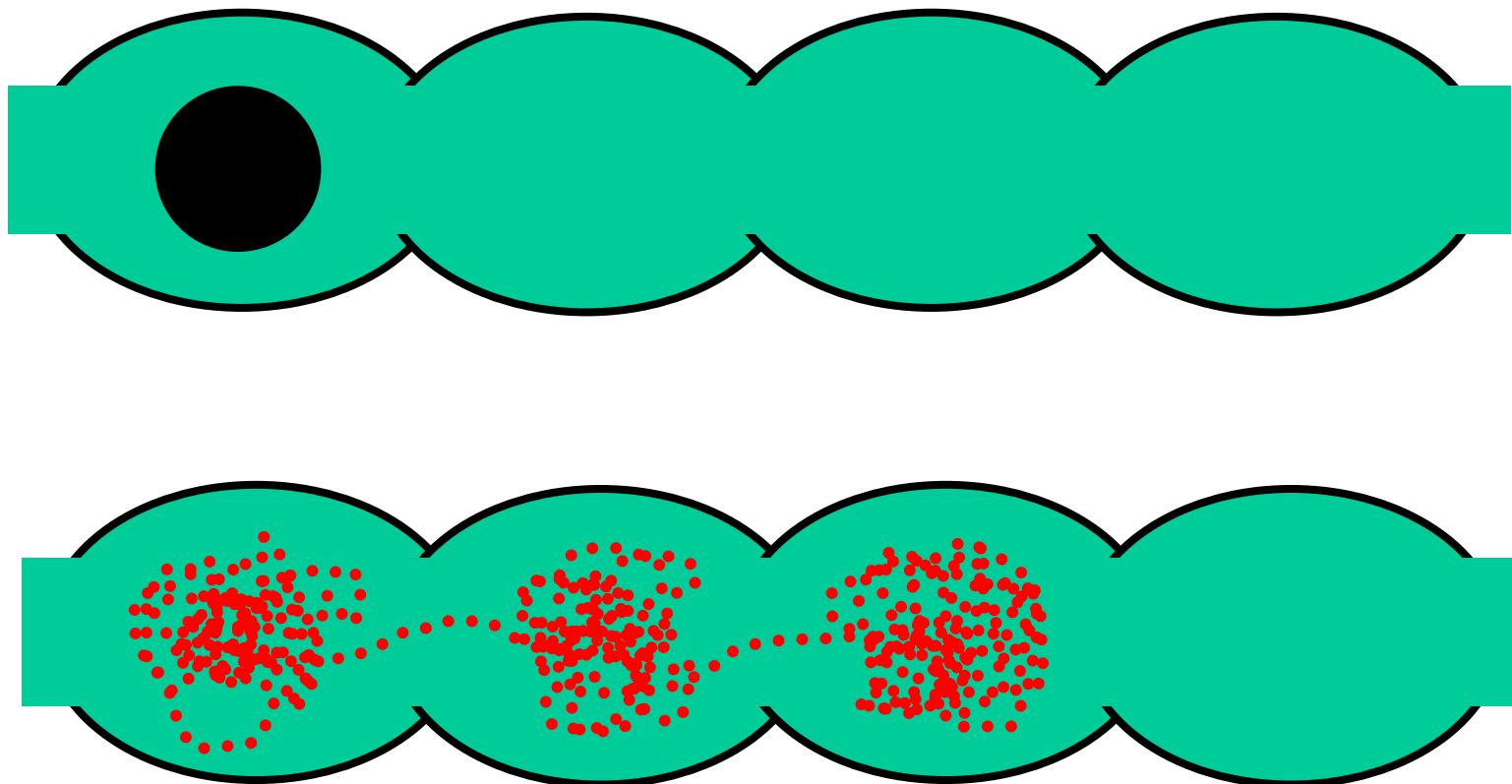
Theory 16.1

Transition state theory 16.1-16.2

Bennett-Chandler Approach 16.2

Transition path ensemble 16.4

Diffusion in porous material



Chemical reaction



Theory:

$$\frac{dc_A(t)}{dt} = -k_{A \rightarrow B} c_A(t) + k_{B \rightarrow A} c_B(t)$$

$$\frac{dc_B(t)}{dt} = +k_{A \rightarrow B} c_A(t) - k_{B \rightarrow A} c_B(t)$$

macroscopic
phenomenological

Total number of molecules

$$\frac{d[c_A(t) + c_B(t)]}{dt} = 0$$

Equilibrium:

$$\dot{c}_A(t) = \dot{c}_B(t) = 0$$

$$\frac{\langle c_A \rangle}{\langle c_B \rangle} = \frac{k_{B \rightarrow A}}{k_{A \rightarrow B}}$$

Make a small perturbation

$$c_A(t) = \langle c_A \rangle + \Delta c_A(t) \quad c_B(t) = \langle c_B \rangle - \Delta c_A(t)$$

$$\frac{d\Delta c_A(t)}{dt} = -k_{A \rightarrow B} \Delta c_A(t) - k_{B \rightarrow A} \Delta c_A(t)$$

$$\Delta c_A(t) = \Delta c_A(0) \exp[-(k_{A \rightarrow B} + k_{B \rightarrow A})t]$$

$$= \Delta c_A(0) \exp[-t/\tau]$$

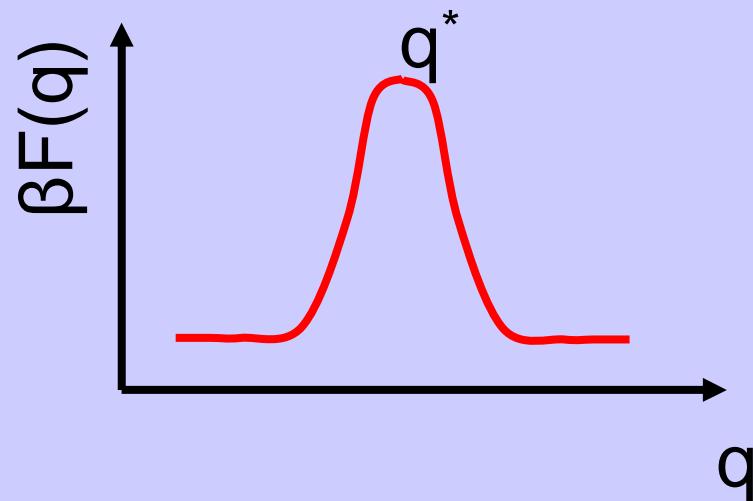
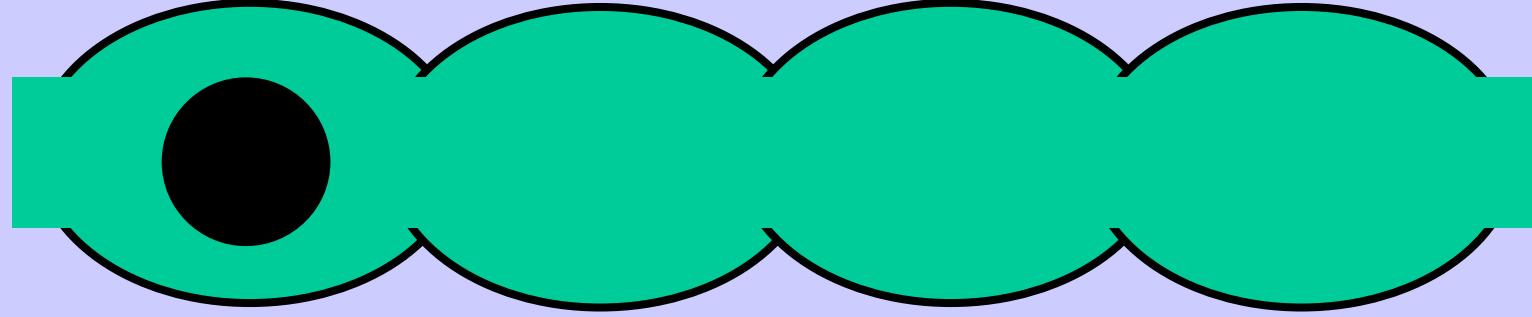
$$\tau = (k_{A \rightarrow B} + k_{B \rightarrow A})^{-1}$$

$$= k_{A \rightarrow B}^{-1} \left(1 + \langle c_A \rangle / \langle c_B \rangle \right)^{-1} = \frac{\langle c_B \rangle}{k_{A \rightarrow B}}$$

Microscopic description of the reaction

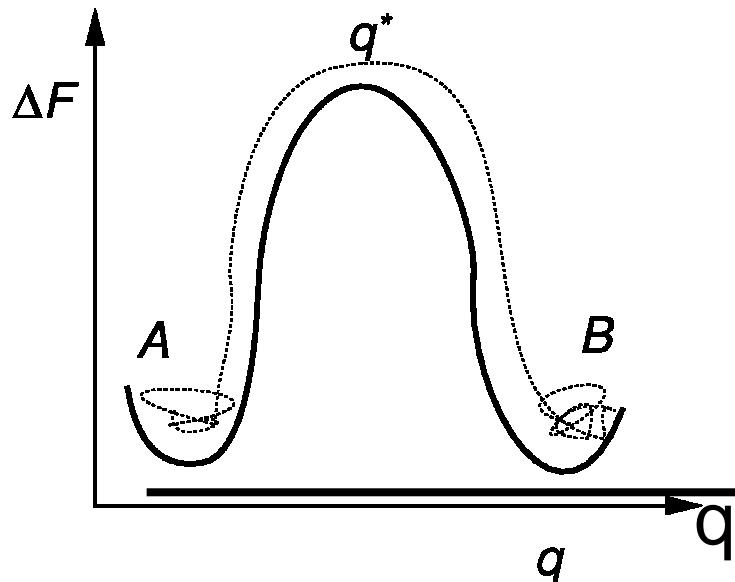
Theory:
microscopic
linear response theory

Reaction coordinate



Microscopic description of the reaction

Reaction coordinate



Theory: microscopic linear response theory

Reactant A: $q < q^*$

Product B: $q > q^*$

Perturbation: $H = H_0 - \varepsilon g_A (q - q^*)$

$$g_A (q - q^*) = 1 - \theta(q - q^*) = \theta(q^* - q)$$

Heaviside θ -function

$$\theta(q - q^*) = \begin{cases} 0 & q - q^* < 0 \\ 1 & q - q^* > 0 \end{cases}$$

$$\Delta c_A = \langle c_A \rangle_\varepsilon - \langle c_A \rangle_0$$

$$\Delta c_A = \langle g_A \rangle_\varepsilon - \langle g_A \rangle_0$$

Probability to be in
state A

Very small perturbation: linear response theory

$$\Delta c_A = \langle g_A \rangle_\varepsilon - \langle g_A \rangle_0$$

$$H = H_0 - \varepsilon g_A (q - q^*)$$

$$\begin{aligned} \frac{\partial \Delta c_A}{\partial \varepsilon} &= \beta \left(\left\langle (g_A)^2 \right\rangle_0 - \langle g_A \rangle_0^2 \right) \\ &= \beta \left(\langle g_A \rangle_0 (1 - \langle g_A \rangle_0) \right) \\ &= \beta \left(\langle c_A \rangle_0 (1 - \langle c_A \rangle_0) \right) = \beta \langle c_A \rangle_0 \langle c_B \rangle_0 \end{aligned}$$

Outside the barrier $g_A = 0$ or 1 :
 $g_A(x) g_A(x) = g_A(x)$

Switch of the perturbation: dynamic linear response

$$\begin{aligned} \Delta c_A(t) &= \Delta c_A(0) \frac{\langle \Delta g_A(0) \Delta g_A(t) \rangle}{\langle c_A \rangle \langle c_B \rangle} \\ &= \Delta c_A(0) \exp[-t/\tau] \end{aligned}$$

Holds for sufficiently long times!

Linear response theory: static

$$H = H_0 - \varepsilon B$$

$$\langle \Delta A \rangle = \langle A \rangle - \langle A \rangle_0$$

$$\langle A \rangle = \frac{\int d\Gamma A \exp[-\beta(H_0 - \varepsilon B)]}{\int d\Gamma \exp[-\beta(H_0 - \varepsilon B)]} \quad \langle A \rangle_0 = \frac{\int d\Gamma A \exp[-\beta H_0]}{\int d\Gamma \exp[-\beta H_0]}$$

$$\left\langle \frac{\partial(\Delta A)}{\partial \varepsilon} \right\rangle = \frac{\int d\Gamma \beta AB \exp[-\beta(H_0 - \varepsilon B)] \int d\Gamma \exp[-\beta(H_0 - \varepsilon B)]}{\left\{ \int d\Gamma \exp[-\beta(H_0 - \varepsilon B)] \right\}^2}$$

$$- \frac{\int d\Gamma A \exp[-\beta(H_0 - \varepsilon B)] \int d\Gamma \beta B \exp[-\beta(H_0 - \varepsilon B)]}{\left\{ \int d\Gamma \exp[-\beta(H_0 - \varepsilon B)] \right\}^2}$$

$$\left\langle \frac{\partial(\Delta A)}{\partial \varepsilon} \right\rangle = \beta \left\{ \langle AB \rangle_0 - \langle A \rangle_0 \langle B \rangle_0 \right\}$$

$$\exp[-t/\tau] = \frac{\langle \Delta g_A(0) \Delta g_A(t) \rangle}{\langle c_A \rangle \langle c_B \rangle}$$

Δ has disappeared because of derivative

Derivative

$$-\frac{1}{\tau} \exp[-t/\tau] = \frac{\langle g_A(0) \dot{g}_A(t) \rangle}{\langle c_A \rangle \langle c_B \rangle} = -\frac{\langle \dot{g}_A(0) g_A(t) \rangle}{\langle c_A \rangle \langle c_B \rangle}$$

For sufficiently short t

$$k_{A \rightarrow B}(t) = \frac{\langle \dot{g}_A(0) g_A(t) \rangle}{\langle c_A \rangle}$$

$$\dot{g}_A(q - q^*) = \dot{q} \frac{\partial g_A(q - q^*)}{\partial q} = -\dot{q} \frac{\partial g_B(q - q^*)}{\partial q}$$

$$k_{A \rightarrow B}(t) = \frac{\left\langle \dot{q}(0) \frac{\partial g_B(q(0) - q^*)}{\partial q} g_B(t) \right\rangle}{\langle c_A \rangle}$$

Stationary

$$\frac{d}{dt} \langle A(t) B(t + t') \rangle = 0$$

$$\langle A(t) \dot{B}(t + t') \rangle + \langle \dot{A}(t) B(t + t') \rangle = 0$$

$$\langle A(0) \dot{B}(t') \rangle = -\langle \dot{A}(0) B(t') \rangle$$

Eyring's transition state theory

$$k_{A \rightarrow B}(t) = \frac{\left\langle \dot{q}(0) \frac{\partial g_B(q(0) - q^*)}{\partial q} g_B(t) \right\rangle}{\langle c_A \rangle}$$

At t=0 particles are at the top of the barrier

Only products contribute to the average

$$= \frac{\left\langle \dot{q}(0) \delta(q(0) - q^*) \theta(q(t) - q^*) \right\rangle}{\langle \theta(q^* - q) \rangle}$$

Let us consider the limit: $t \rightarrow 0^+$

$$\lim_{t \rightarrow 0^+} \theta(q(t) - q^*) = \theta(\dot{q}(t))$$
$$k_{A \rightarrow B}^{TST}(t) = \frac{\left\langle \dot{q}(0) \delta(q(0) - q^*) \theta(\dot{q}) \right\rangle}{\langle \theta(q^* - q) \rangle}$$

$$g_B(q - q^*) = 1 - g_A(q - q^*) = \theta(q - q^*)$$

$$g_A(q - q^*) = 1 - \theta(q - q^*) = \theta(q^* - q)$$

$$\frac{\partial g_B(q - q^*)}{\partial q} = \delta(q - q^*)$$

Bennett-Chandler approach

Conditional average: $\langle \dot{q}(0) \theta(q(t) - q^*) \rangle$
given that we start on top of the barrier

$$k_{A \rightarrow B}(t) = \frac{\langle \dot{q}(0) \delta(q(0) - q^*) \theta(q(t) - q^*) \rangle}{\langle \theta(q^* - q) \rangle}$$

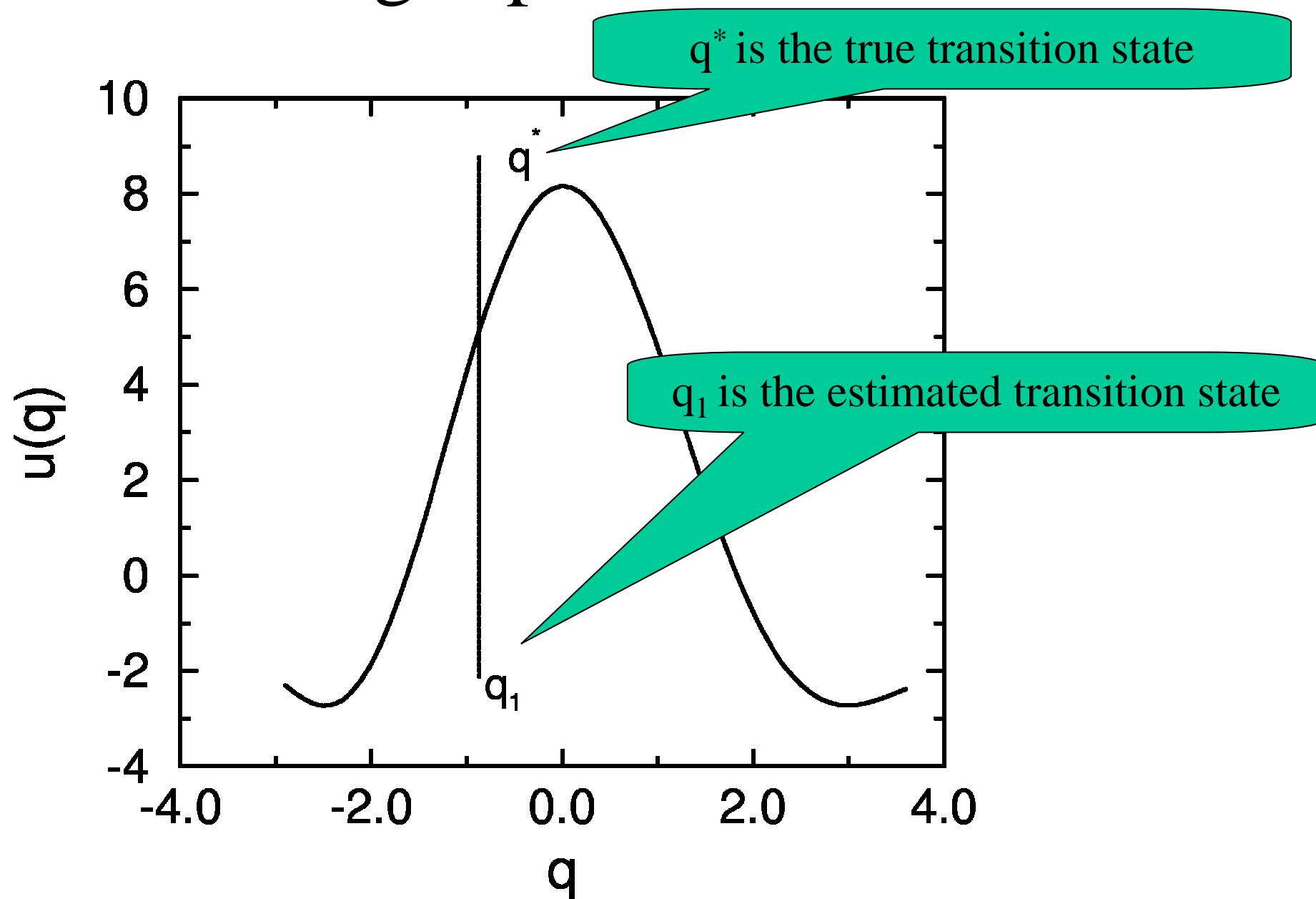
$$k_{A \rightarrow B}(t) = \frac{\langle \dot{q}(0) \delta(q(0) - q^*) \theta(q(t) - q^*) \rangle}{\langle \delta(q(0) - q^*) \rangle} \times \frac{\langle \delta(q(0) - q^*) \rangle}{\langle \theta(q^* - q) \rangle}$$

Computational scheme:

Probability to find q on top of the barrier

1. Determine the probability from the free energy
2. Compute the conditional average from a MD simulation

Ideal gas particle and a hill



The motion of the particle is ballistic

Transition

In the product or reactant state in can exchange energy

$$k_{A \rightarrow B}^{TST}(t) = \frac{\langle \dot{q}(0) \delta(q(0) - q_1) \theta(\dot{q}) \rangle}{\langle \delta(q(0) - q_1) \rangle} \times \frac{\langle \delta(q(0) - q_1) \rangle}{\langle \theta(q_1 - q) \rangle}$$

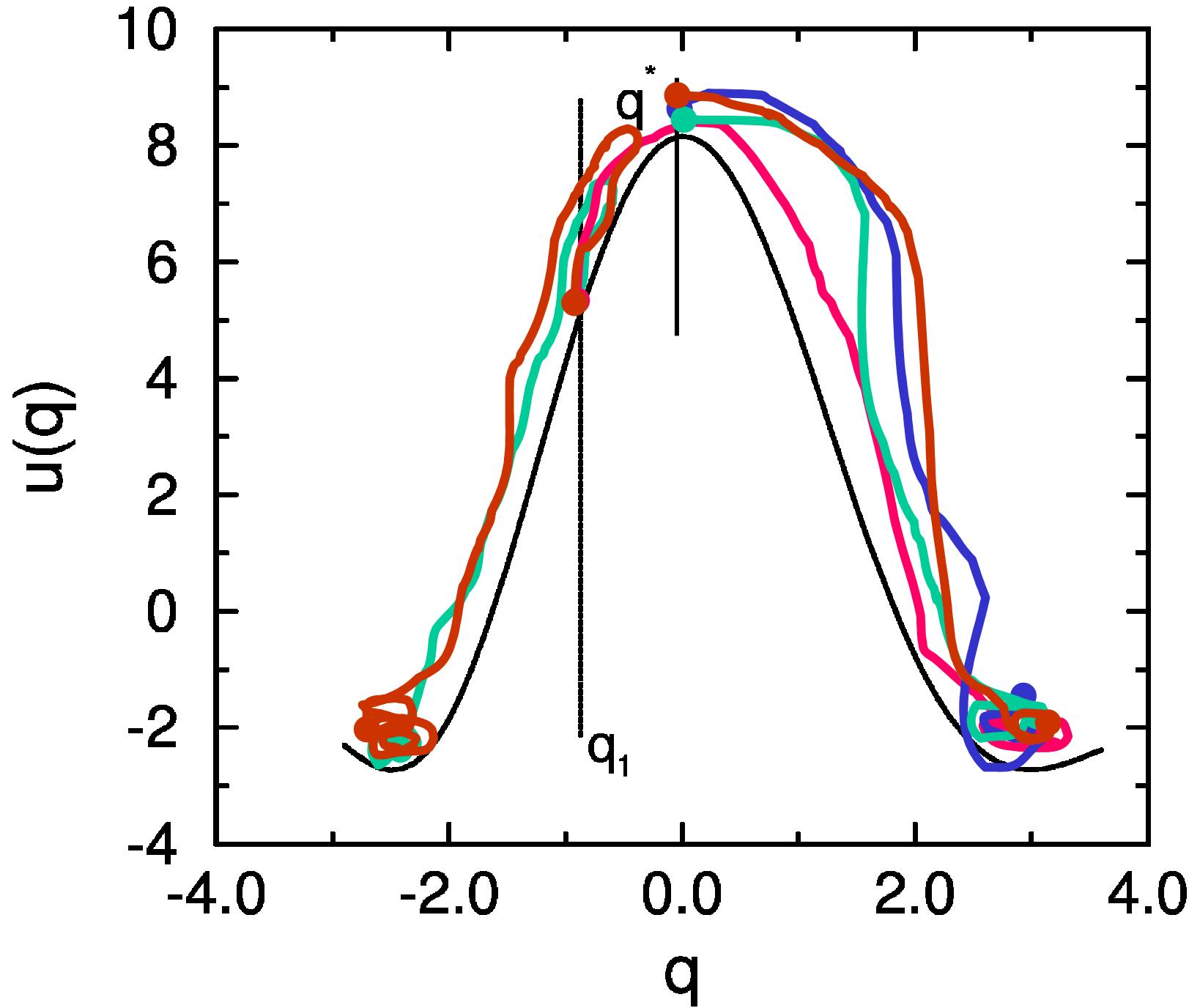
Assumed transition state

$$\begin{aligned} \frac{\langle \delta(q(0) - q_1) \rangle}{\langle \theta(q_1 - q) \rangle} &= \frac{\int dq \delta(q(0) - q_1) \exp[-\beta U(q)]}{\int dq \delta(q(0) - q_1) \exp[-\beta U(q)]} \\ &= \frac{\exp[-\beta U(q_1)]}{\int_{-\infty}^{q_1} dq \exp[-\beta U(q)]} \end{aligned}$$

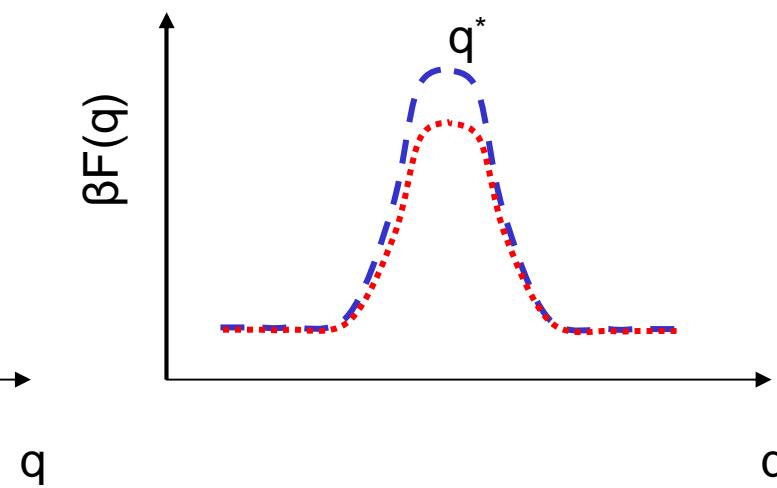
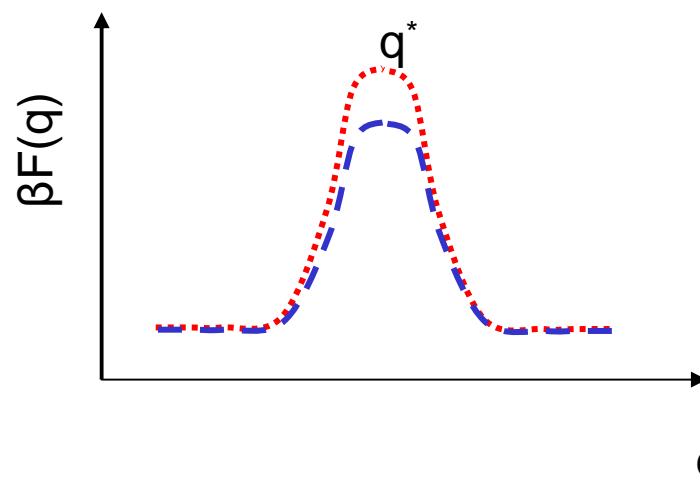
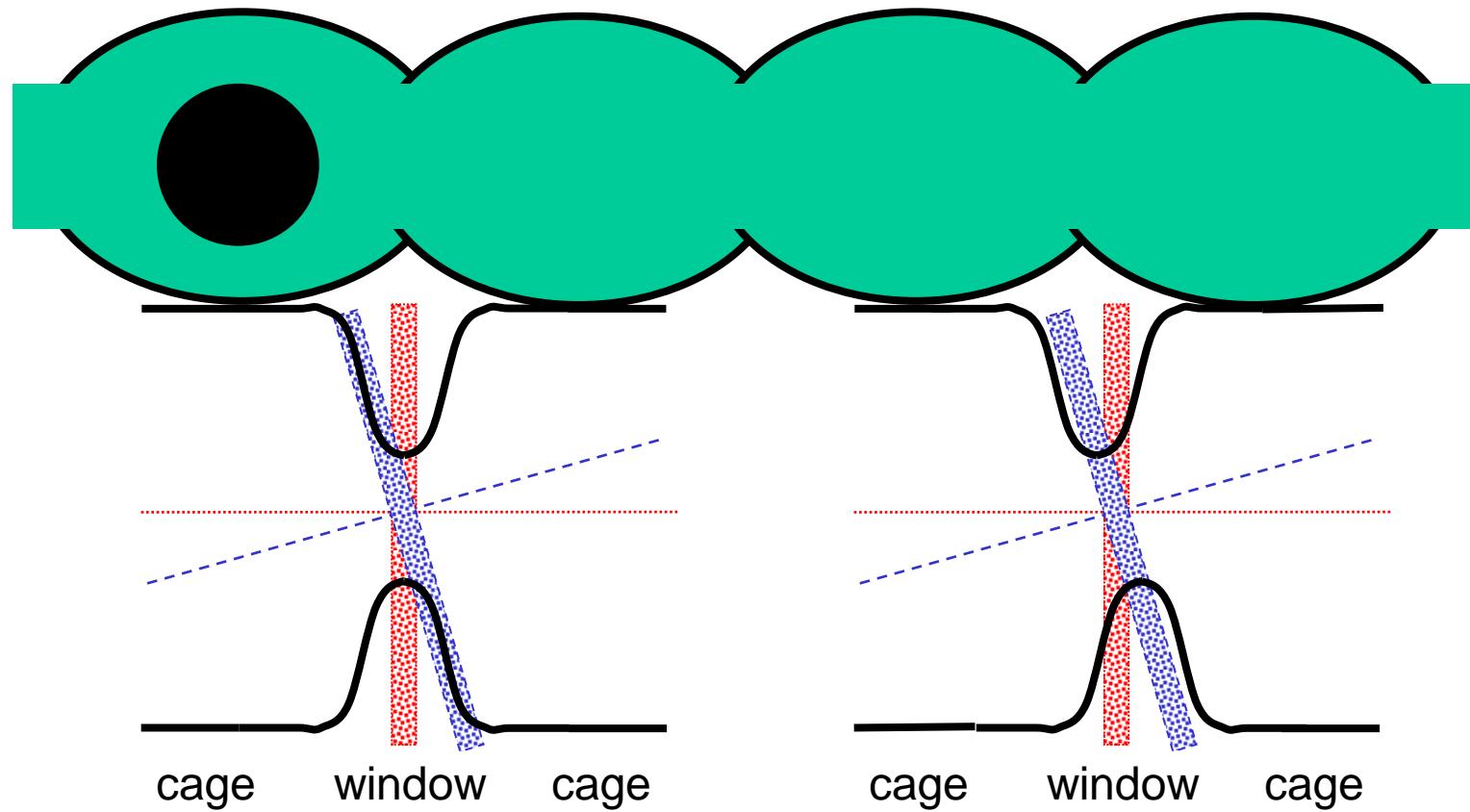
$$\begin{aligned} \frac{\langle \dot{q}(0) \delta(q(0) - q_1) \theta(\dot{q}) \rangle}{\langle \delta(q(0) - q_1) \rangle} &= \frac{\int dq \dot{q}(0) \delta(q(0) - q_1) \theta(\dot{q}) \exp[-\beta U(q)]}{\int dq \delta(q(0) - q_1) \exp[-\beta U(q)]} \\ &= 0.5 |\dot{q}(0)| \frac{\int dq \delta(q(0) - q_1) \exp[-\beta U(q)]}{\int dq \delta(q(0) - q_1) \exp[-\beta U(q)]} \\ &= 0.5 |\dot{q}(0)| \end{aligned}$$

$$k_{A\rightarrow B}^{TST}\left(t\right) =0.5\left| \dot{q}\left(0\right) \right| \frac{\exp\left[-\beta U\left(q_1\right) \right] }{\int\limits_{-\infty}^{q_1}\mathrm{d}q\exp\left[-\beta U\left(q\right) \right] }$$

$$=\sqrt{\frac{k_BT}{2\pi m}}\frac{\exp\left[-\beta U\left(q_1\right) \right] }{\int\limits_{-\infty}^{q_1}\mathrm{d}q\exp\left[-\beta U\left(q\right) \right] }$$

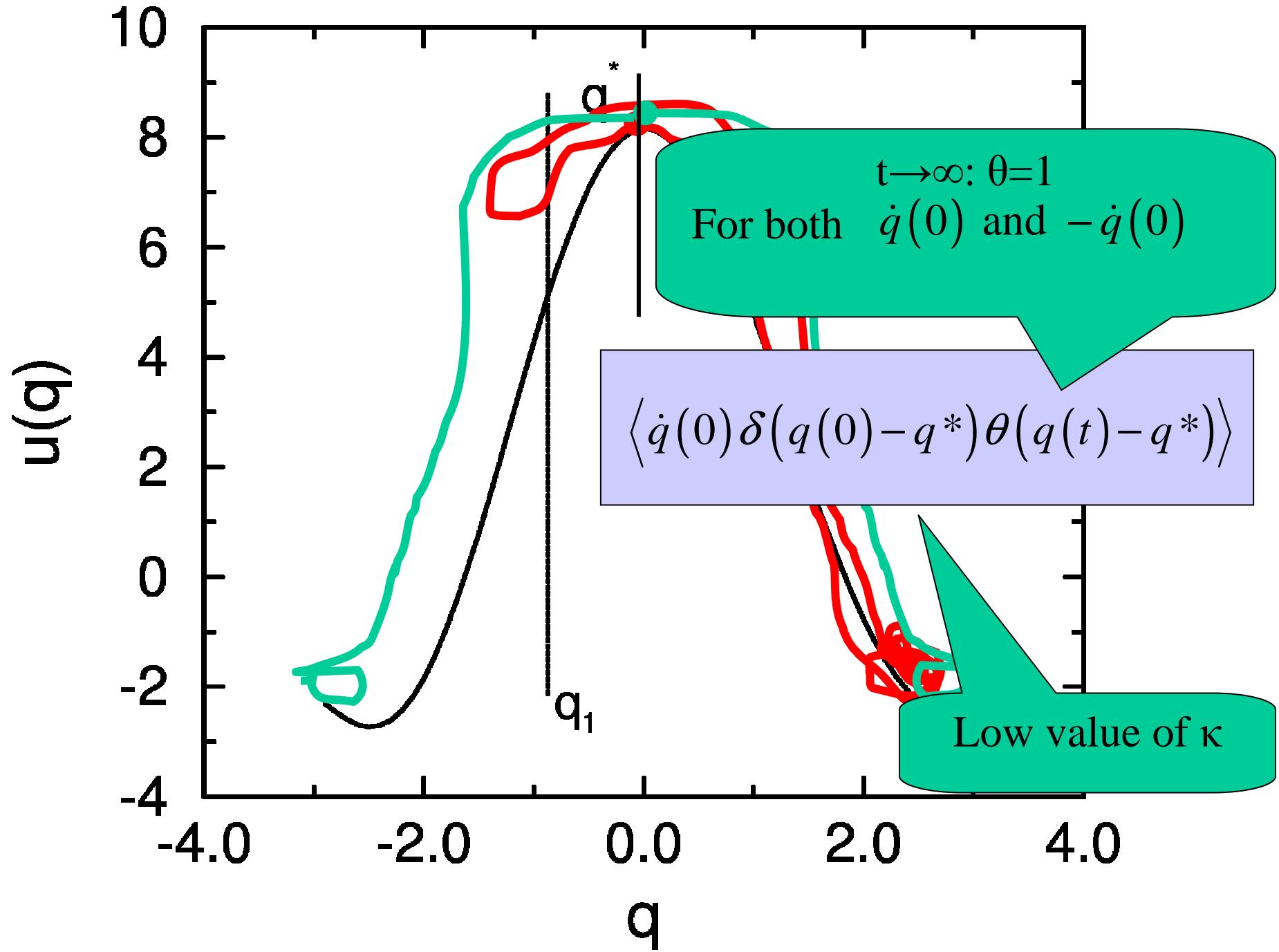


Reaction coordinate



Transition state theory

- One has to know the free energy accurately
- Gives an upper bound to the reaction rate
- Assumptions underlying transition theory should hold: *no recrossings*



$$k_{A \rightarrow B}^{TST}(t) = \frac{\langle \dot{q}(0) \delta(q(0) - q_1) \theta(\dot{q}) \rangle}{\langle \delta(q(0) - q_1) \rangle} \times \frac{\langle \delta(q(0) - q_1) \rangle}{\langle \theta(q_1 - q) \rangle}$$

Bennett
Chandler
Approach

Transmission coefficient

$$\kappa(t) \equiv \frac{k_{A \rightarrow B}(t)}{k_{A \rightarrow B}^{TST}}$$

MD simulation:

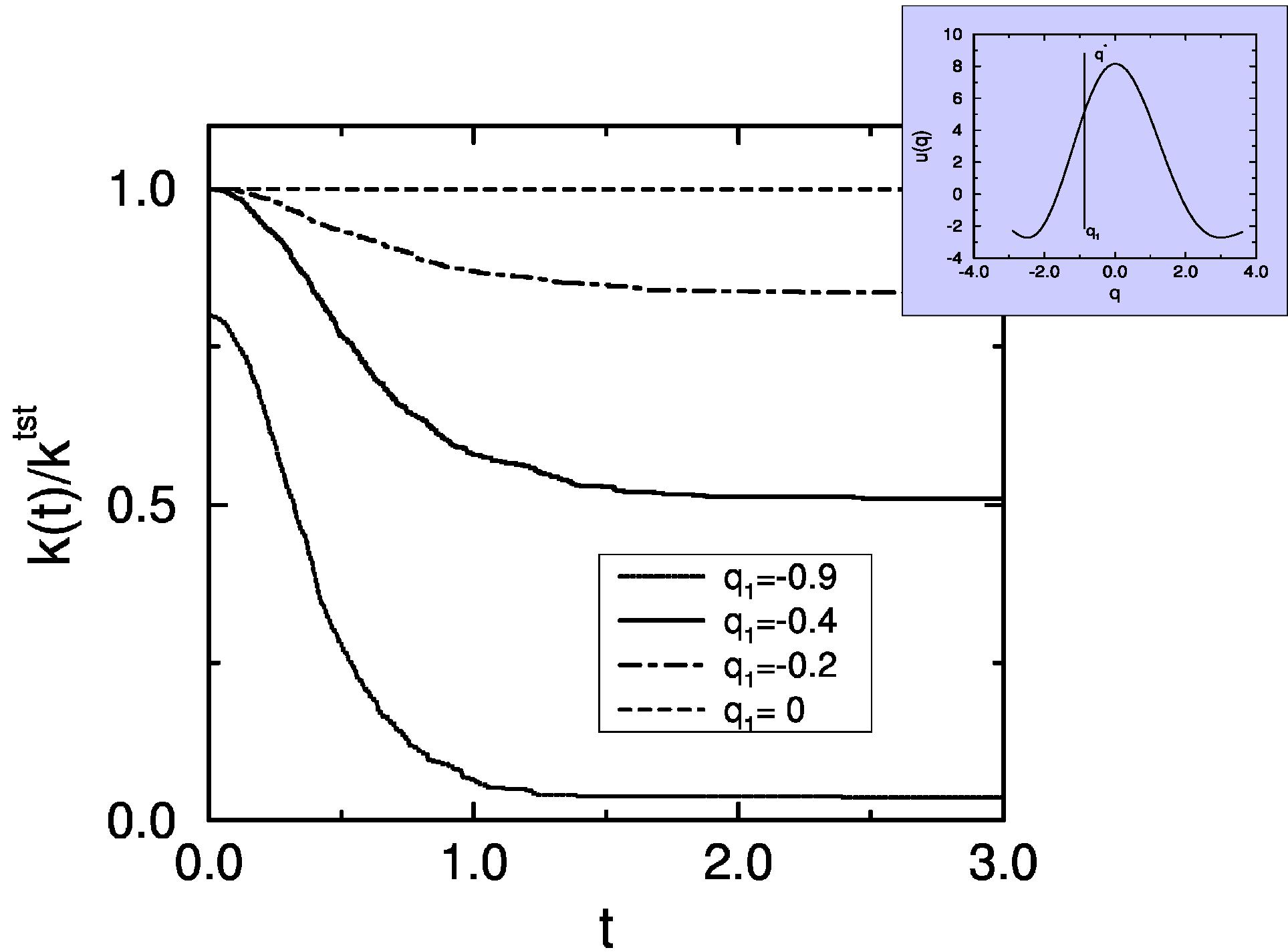
1. At $t=0$ $q=q_1$
2. Determine the fraction at the product state weighted with the initial velocity

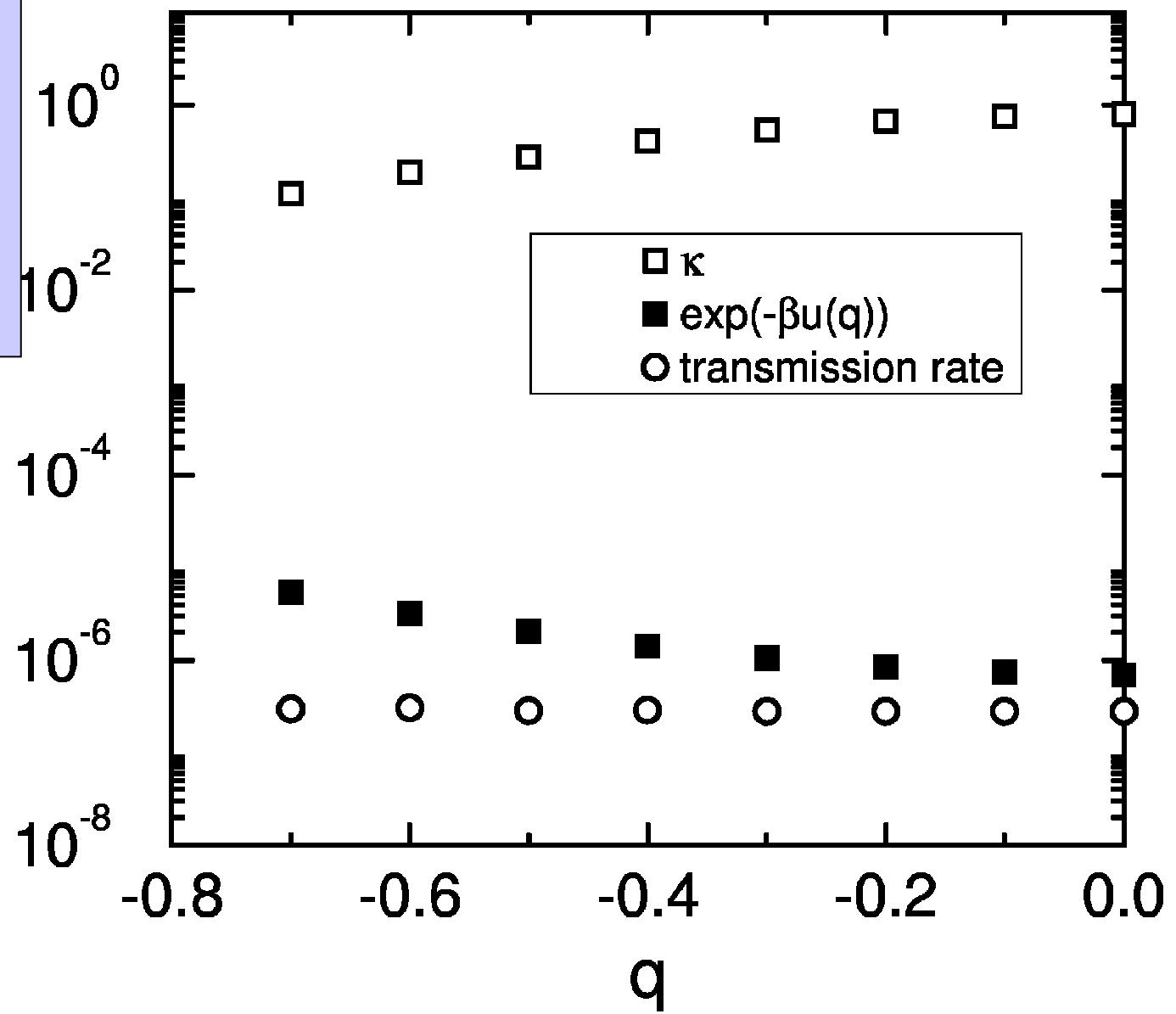
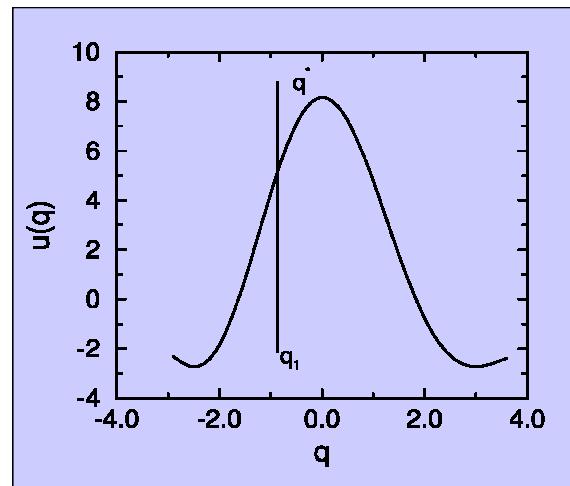
$$= \frac{\langle \dot{q}(0) \delta(q(0) - q_1) \theta(q(t) - q_1) \rangle}{0.5 |\dot{q}(0)|}$$

MD simulation to correct the transition state result!

$$k_{A \rightarrow B}^{TST}(t) = 0.5 \left| \dot{q}(0) \right| \frac{\exp[-\beta U(q_1)]}{\int\limits_{-\infty}^{q_1} dq \exp[-\beta U(q)]}$$

$$= \sqrt{\frac{k_B T}{2\pi m}} \frac{\exp[-\beta U(q_1)]}{\int\limits_{-\infty}^{q_1} dq \exp[-\beta U(q)]}$$

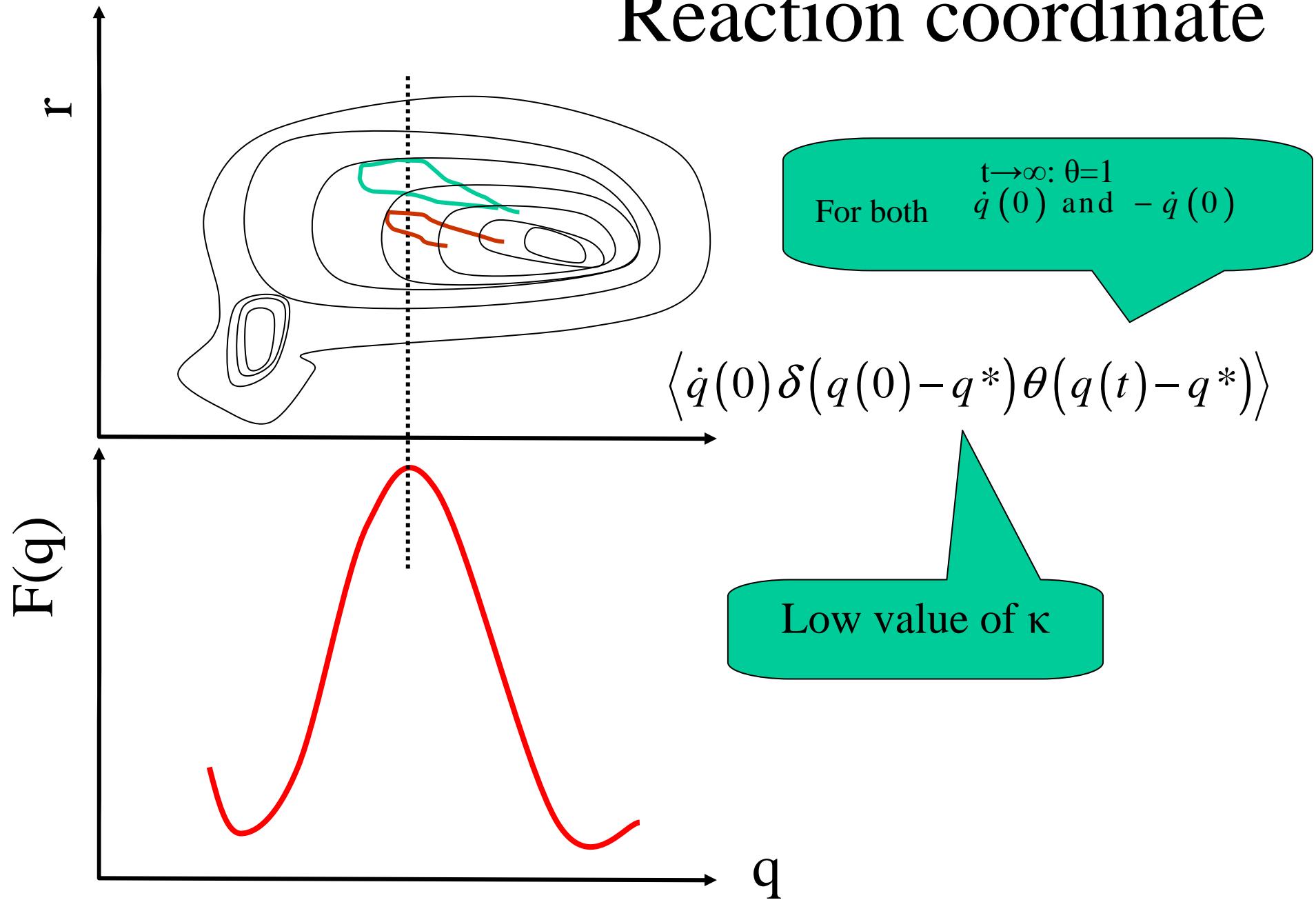




Bennett-Chandler approach

- Results are independent of the precise location of the estimate of the transition state, but the accuracy does.
- If the transmission coefficient is very low
 - Poor estimate of the reaction coordinate
 - Diffuse barrier crossing

Reaction coordinate



Transition path sampling

$$\exp[-t/\tau] = \frac{\langle \Delta g_A(0) \Delta g_A(t) \rangle}{\langle c_A \rangle \langle c_B \rangle}$$

x_t is fully determined by the initial condition

$$C(t) = \frac{\langle h_A(x_0) h_B(x_t) \rangle}{\langle h_A \rangle} \approx \langle h_B \rangle [1 - \exp(-t/\tau)]$$

$$h_A = \begin{cases} 1 & \text{in } A \\ 0 & \text{elsewhere} \end{cases}$$

Path that starts at A and is in time t in B:
importance sampling
in these paths

$$C(t) = \frac{\int dx_0 N(x_0) h_A(x_0) h_B(x_t)}{\int dx_0 N(x_0) h_A(x_0)}$$

$$C(t) = \langle h_B(x_t) \rangle_{A,t} \quad P(\text{path}) = h_A(x_0) N(x_0)$$

$$\begin{aligned}
C(t) &= \frac{\langle h_A(x_0) h_B(x_t) \rangle}{\langle h_A(x_0) \rangle} \\
&= \frac{\langle h_A(x_0) h_B(x_t) \rangle}{\langle h_A(x_0) h_B(x_t') \rangle} \frac{\langle h_A(x_0) h_B(x_t') \rangle}{\langle h_A(x_0) \rangle} \\
&= \frac{\langle h_A(x_0) h_B(x_t) \rangle}{\langle h_A(x_0) h_B(x_t') \rangle} C(t')
\end{aligned}$$

