

# Advanced Monte Carlo different ensembles

# Recall

- NVT simulations
  - Detailed balance
  - Generate a Boltzmann distribution
- Non-Boltzmann sampling
  - Recover correct sampling from a non-Boltzmann distribution
- Biased Monte Carlo
  - Bias the sampling
  - Remove the bias by changing the acceptance rule

# Non-Boltzmann sampling

$$\langle A \rangle_{NVT_1} = \frac{1}{Q_{NVT_1}} \frac{1}{\Lambda^{3N} N!} \int d\mathbf{r}^N A(\mathbf{r}^N) \exp[-\beta_1 U(\mathbf{r}^N)]$$

$$= \frac{\int d\mathbf{r}^N A(\mathbf{r}^N) \exp[-\beta_1 U(\mathbf{r}^N)]}{\int d\mathbf{r}^N \exp[-\beta_1 U(\mathbf{r}^N)]}$$

Why are we not using this?

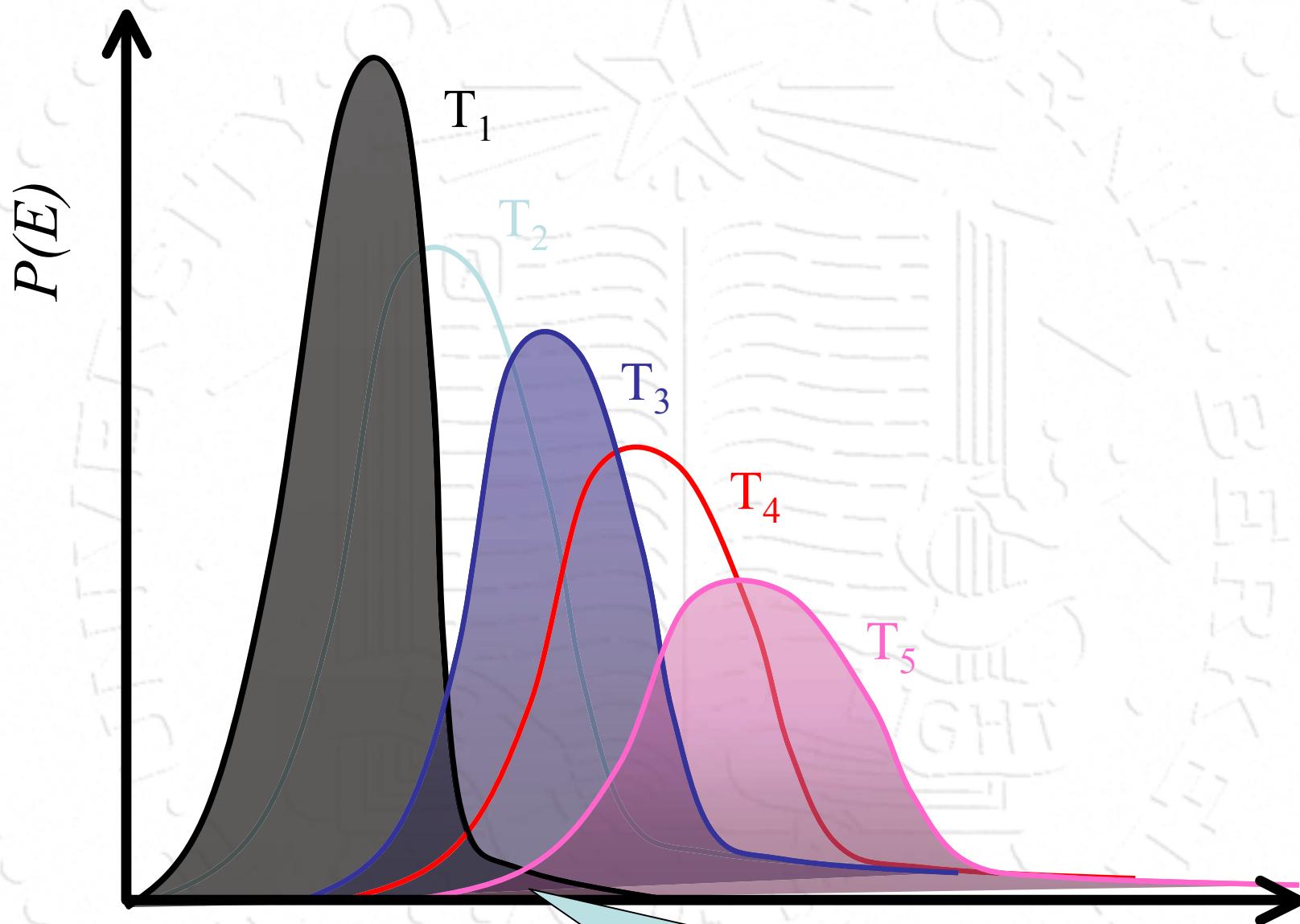
$T_1$  is arbitrary!

$$= \frac{\int d\mathbf{r}^N A(\mathbf{r}^N) \exp[-\beta_1 U(\mathbf{r}^N)]}{\int d\mathbf{r}^N \exp[-\beta_1 U(\mathbf{r}^N)] \exp[\beta_2 U(\mathbf{r}^N) - \beta_2 U(\mathbf{r}^N)]}$$

We only need  
a *single*  
simulation!

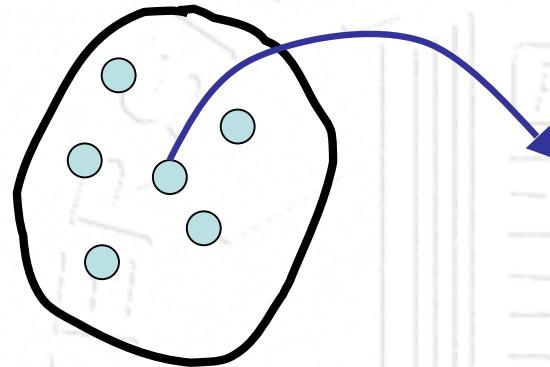
We perform a simulation at  $T=T_2$   
and  
we determine  $A$  at  $T=T_1$

$$= \frac{\langle A \exp[(\beta_2 - \beta_1)U] \rangle_{NVT_2}}{\langle \exp[(\beta_2 - \beta_1)U] \rangle_{NVT_2}}$$



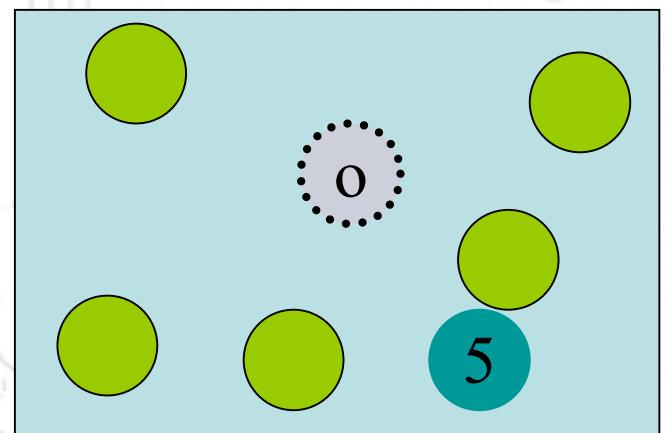
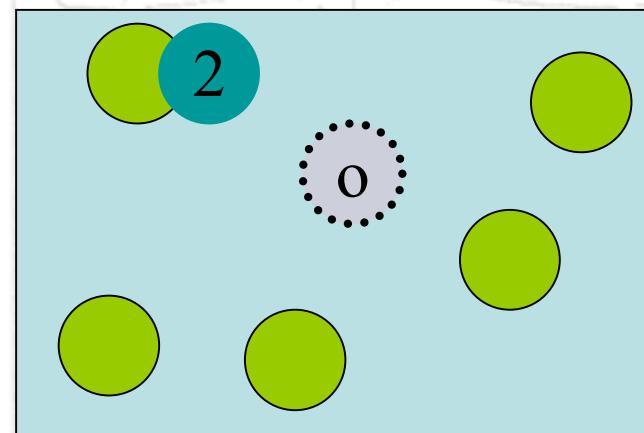
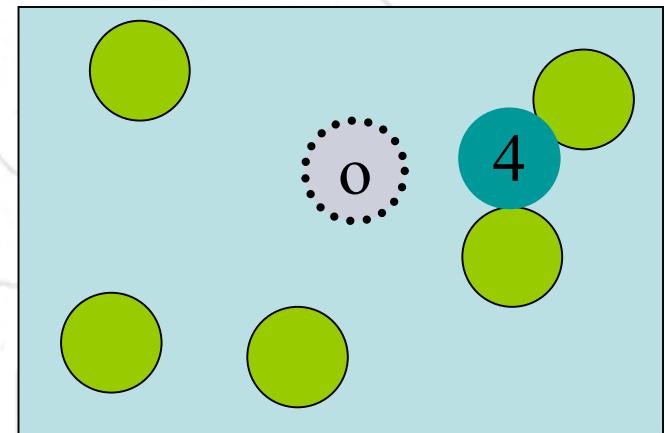
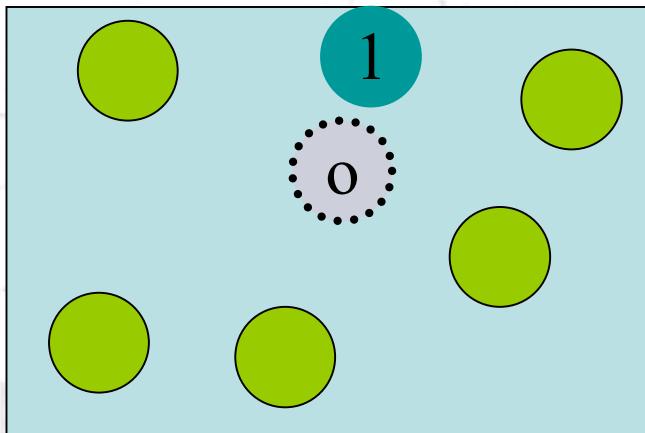
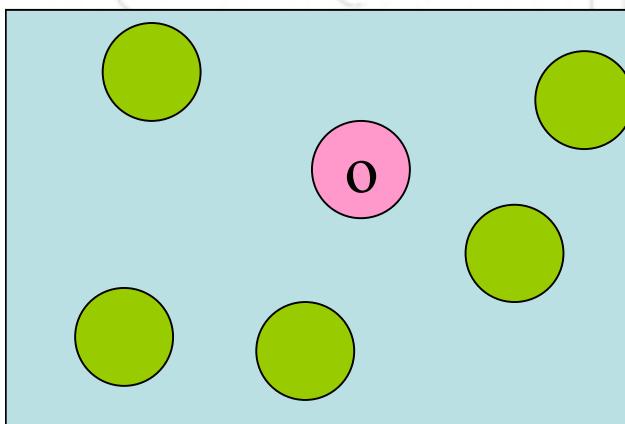
Overlap becomes very small

# How to do *parallel* Monte Carlo

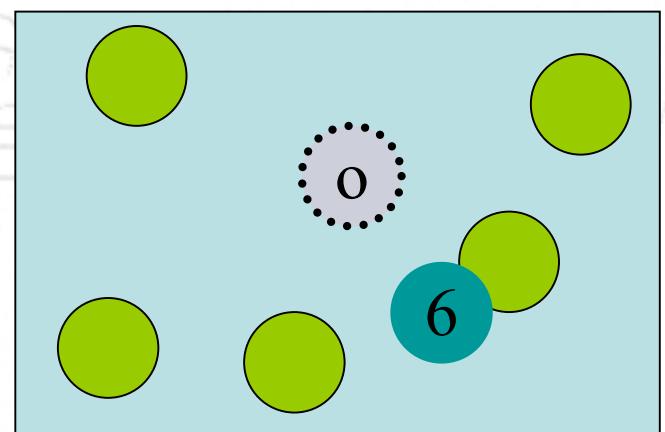
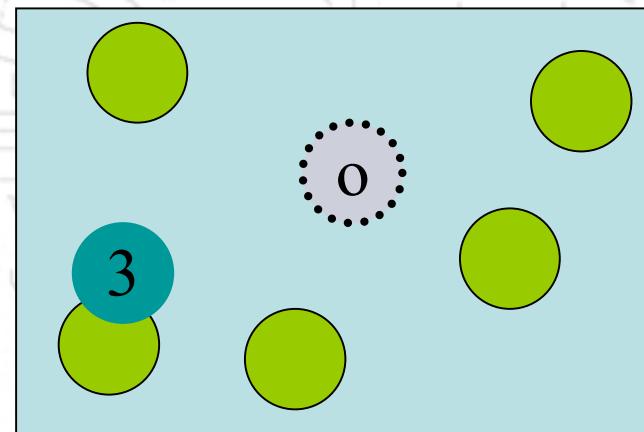


- Is it possible to do Monte Carlo in parallel
  - Monte Carlo is sequential!
  - We first have to know the result of the current move before we can continue!

# Parallel Monte Carlo



$$P(n) = \frac{\exp[-\beta(U_n)]}{\sum_{j=1}^g \exp[-\beta(U_j)]}$$



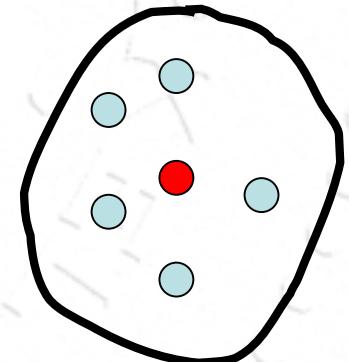
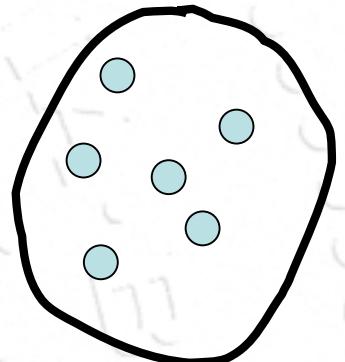
$$K(o \rightarrow n) = N(o) \times \alpha(o \rightarrow n) \times \text{acc}(o \rightarrow n)$$

$$\alpha(o \rightarrow n) = \frac{\exp[-\beta(U_n)]}{\sum_{j=1}^g \exp[-\beta(U_j)]}$$

$$\alpha(o \rightarrow n) = \frac{\exp[-\beta(U_n)]}{W(\textcolor{red}{n})}$$

$$\alpha(n \rightarrow o) = \frac{\exp[-\beta(U_o)]}{\sum_{j=1}^g \exp[-\beta(U_j)]}$$

$$\alpha(n \rightarrow o) = \frac{\exp[-\beta(U_o)]}{W(\textcolor{red}{o})}$$



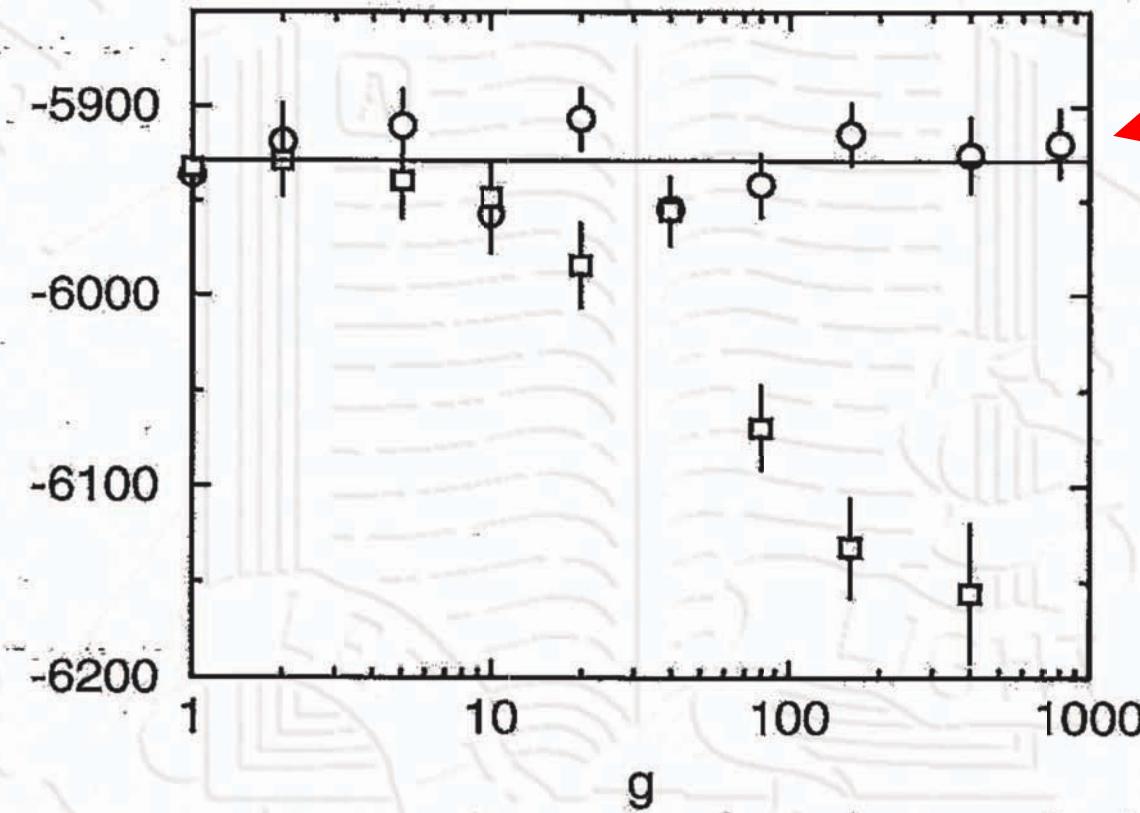
$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n) \times \alpha(n \rightarrow o)}{N(o) \times \alpha(o \rightarrow n)}$$

$$\alpha(o \rightarrow n) = \frac{\exp[-\beta(U_n)]}{W(\textcolor{red}{n})}$$

$$\alpha(n \rightarrow o) = \frac{\exp[-\beta(U_o)]}{W(\textcolor{red}{o})}$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n) \times \frac{\exp[-\beta(U_o)]}{W(\textcolor{red}{o})}}{N(o) \times \frac{\exp[-\beta(U_n)]}{W(\textcolor{red}{n})}} = \frac{W(n)}{W(o)}$$

# Modified acceptance rule



Modified acceptance rule remove the *bias* exactly!

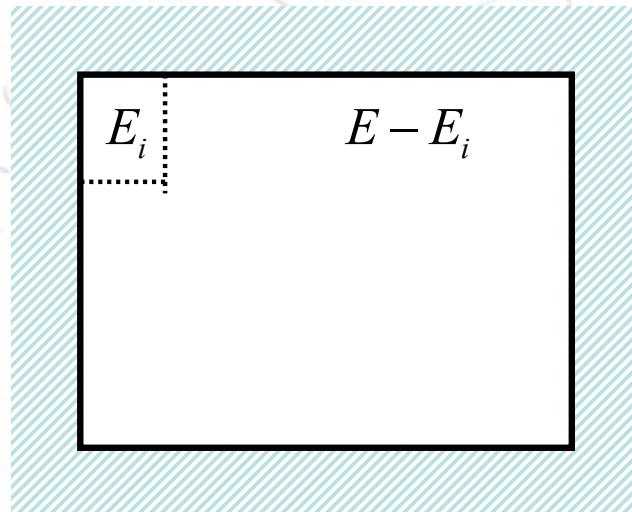
# Ensembles

- Micro-canonical ensemble:  $E, V, N$
- Canonical ensemble:  $T, V, N$
- Constant pressure ensemble:  $T, P, N$
- Grand-canonical ensemble:  $T, V, \mu$

# Canonical ensemble

$1/k_B T$

Consider a small system that can exchange heat with a big reservoir



$$\ln \Omega(E - E_i) = \ln \Omega(E) - \frac{\partial \ln \Omega}{\partial E} E_i + \dots$$

$$\ln \frac{\Omega(E - E_i)}{\Omega(E)} = -\frac{E_i}{k_B T}$$

Hence, the probability to find  $E_i$ :

$$P(E_i) = \frac{\Omega(E - E_i)}{\sum_j \Omega(E - E_j)} = \frac{\exp(-E_i/k_B T)}{\sum_j \exp(-E_j/k_B T)}$$

$$P(E_i) \propto \exp(-E_i/k_B T)$$

Boltzmann distribution

# Statistical Thermodynamics

Partition function

$$Q_{NVT} = \frac{1}{\Lambda^{3N} N!} \int d\mathbf{r}^N \exp[-\beta U(\mathbf{r}^N)]$$

Ensemble average

$$\langle A \rangle_{NVT} = \frac{1}{Q_{NVT}} \frac{1}{\Lambda^{3N} N!} \int d\mathbf{r}^N A(\mathbf{r}^N) \exp[-\beta U(\mathbf{r}^N)]$$

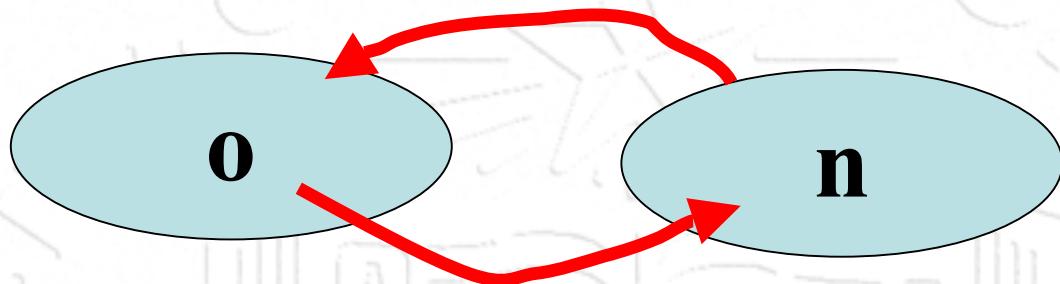
Probability to find a particular configuration

$$N(\mathbf{r}^N) = \frac{1}{Q_{NVT}} \frac{1}{\Lambda^{3N} N!} \int d\mathbf{r}'^N \delta(\mathbf{r}'^N - \mathbf{r}^N) \exp[-\beta U(\mathbf{r}'^N)] \propto \exp[-\beta U(\mathbf{r}^N)]$$

Free energy

$$\beta F = -\ln(Q_{NVT})$$

# Detailed balance



$$K(o \rightarrow n) = K(n \rightarrow o)$$

$$K(o \rightarrow n) = N(o) \times \alpha(o \rightarrow n) \times \text{acc}(o \rightarrow n)$$

$$K(n \rightarrow o) = N(n) \times \alpha(n \rightarrow o) \times \text{acc}(n \rightarrow o)$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n) \times \alpha(n \rightarrow o)}{N(o) \times \alpha(o \rightarrow n)} = \frac{N(n)}{N(o)}$$

# $NVT$ -ensemble

$$N(n) \propto \exp[-\beta U(n)]$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n)}{N(o)}$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \exp[-\beta[U(n) - U(o)]]$$

## Algorithm 2 (Attempt to Displace a Particle)

```
SUBROUTINE mcmove  
  
o=int(ranf()*npart)+1  
call ener(x(o),eno)  
xn=x(o)+(ranf()-0.5)*delx  
call ener(xn,enn)  
if (ranf().lt.exp(-beta  
+ * (enn-eno)) x(o)=xn  
return  
end
```

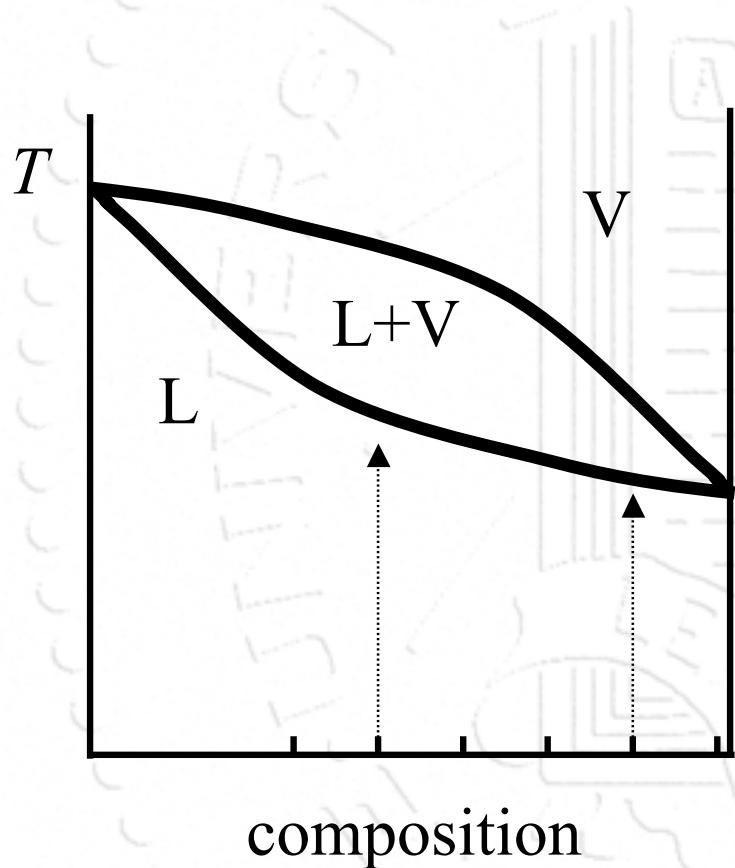
attempts to displace a particle

select a particle at random  
energy old configuration  
give particle random displacement  
energy new configuration  
acceptance rule (3.2.1)  
accepted: replace  $x(o)$  by  $xn$

Comments to this algorithm:

1. Subroutine `ener` calculates the energy of a particle at the given position.
2. Note that, if a configuration is rejected, the old configuration is retained.
3. The `ranf()` is a random number uniform in  $[0, 1]$ .

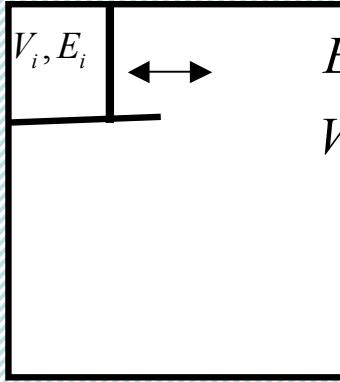
# Example (1): vapour-liquid equilibrium mixture



Measure the composition of the coexisting vapour and liquid phases if we start with a homogeneous liquid of two different compositions:

- Mimic this with the  $N, V, T$  ensemble?
- Or simulate at constant pressure?

# Constant pressure simulations: N P T ensemble



## Thermo recall (4)

First law of thermodynamics

$$dE = TdS - pdV + \sum_i \mu_i dN_i$$

Hence

$$\frac{1}{T} = \left( \frac{\partial S}{\partial E} \right)_{V,N}$$

and

$$\left( \frac{\partial S}{\partial V} \right)_{T,N} = \frac{p}{T}$$

Hence, the probability

$$P(E_i, V_i) = \frac{\beta (E_i + pV_i)]}{\sum_{j,k} \Omega(E - E_j, V - V_k) \sum_{j,k} \exp[-\beta (E_j + pV_k)]}$$

$$\propto \exp[-\beta (E_i + pV_i)]$$

$p/k_B T$

in that can exchange with a big reservoir

# NPT Ensemble

Partition function:

$$Q_{NPT} = \frac{\beta P}{N! \Lambda^{3N}} \int dV \exp[-\beta PV] \int dr^N \exp[-\beta U(r^N)]$$

Scaled coordinates  $s_x = r_x / L_x$

$$Q_{NPT} = \frac{\beta P}{N! \Lambda^{3N}} \int dV \exp[-\beta PV] V^N \int ds^N \exp[-\beta U(s^N; L)]$$

Probability to find a particular configuration:

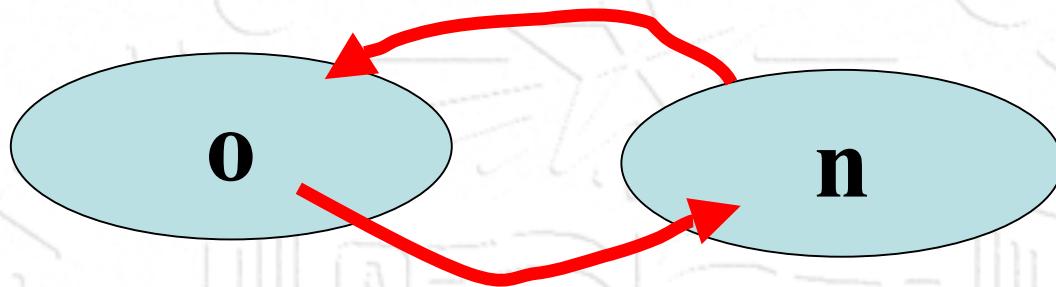
$$N_{NPT}(V, s^N) \propto V^N \exp[-\beta PV] \exp[-\beta U(s^N; L)]$$

Sample a particular configuration:

- Change of volume
- Change of reduced coordinates

Acceptance rules ??

# Detailed balance



$$K(o \rightarrow n) = K(n \rightarrow o)$$

$$K(o \rightarrow n) = N(o) \times \alpha(o \rightarrow n) \times \text{acc}(o \rightarrow n)$$

$$K(n \rightarrow o) = N(n) \times \alpha(n \rightarrow o) \times \text{acc}(n \rightarrow o)$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n) \times \alpha(n \rightarrow o)}{N(o) \times \alpha(o \rightarrow n)} = \frac{N(n)}{N(o)}$$

# $NPT$ -ensemble

$$N_{NPT}(V, \mathbf{s}^N) \propto V^N \exp[-\beta PV] \exp[-\beta U(\mathbf{s}^N; L)]$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n)}{N(o)}$$

Suppose we change the position of a randomly selected particle

$$\begin{aligned} \frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} &= \frac{V^N \exp[-\beta PV] \exp[-\beta U(s_n^N; L)]}{V^N \exp[-\beta PV] \exp[-\beta U(s_o^N; L)]} \\ &= \frac{\exp[-\beta U(s_n^N; L)]}{\exp[-\beta U(s_o^N; L)]} = \exp\{-\beta[U(n) - U(o)]\} \end{aligned}$$

# *NPT*-ensemble

$$N_{NPT}(V, \mathbf{s}^N) \propto V^N \exp[-\beta PV] \exp[-\beta U(\mathbf{s}^N; L)]$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n)}{N(o)}$$

Suppose we change the *volume* of the system

$$\begin{aligned} \frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} &= \frac{V_n^N \exp[-\beta P V_n] \exp[-\beta U(\mathbf{s}^N; L_n)]}{V_o^N \exp[-\beta P V_o] \exp[-\beta U(\mathbf{s}^N; L_o)]} \\ &= \left( \frac{V_n}{V_o} \right)^N \exp[-\beta P(V_n - V_o)] \exp\{-\beta[U(n) - U(0)]\} \end{aligned}$$

# Algorithm: NPT

- Randomly change the position of a particle
- Randomly change the volume

## Algorithm 10 (Basic NPT-Ensemble Simulation)

PROGRAM mc_npt	basic NPT ensemble simulation
do 1cycl=1,ncycl	perform ncycl MC cycles
ran=ranf()*(npart+1)+1	
if (ran.le.npart) then	perform particle displacement
call mcmove	
else	perform volume change
call mcvol	
endif	
if (mod(1cycl,nsamp).eq.0)	sample averages
+    call sample	
enddo	
end	

## Algorithm 2 (Attempt to Displace a Particle)

```
SUBROUTINE mcmove  
  
o=int(ranf()*npart)+1  
call ener(x(o),eno)  
xn=x(o)+(ranf()-0.5)*delx  
call ener(xn,enn)  
if (ranf().lt.exp(-beta  
+ * (enn-eno)) x(o)=xn  
return  
end
```

attempts to displace a particle

select a particle at random  
energy old configuration  
give particle random displacement  
energy new configuration  
acceptance rule (3.2.1)  
accepted: replace  $x(o)$  by  $xn$

Comments to this algorithm:

1. Subroutine `ener` calculates the energy of a particle at the given position.
2. Note that, if a configuration is rejected, the old configuration is retained.
3. The `ranf()` is a random number uniform in  $[0, 1]$ .

## Algorithm 11 (Attempt to Change the Volume)

SUBROUTINE mcvol

```
call toterg(box, eno)
vo=box**3
lnvn=log(vo)+(ranf()-0.5)*vmax
vn=exp(lnvn)
boxn=vn**(1/3)
do i=1,npart
    x(i)=x(i)*boxn/box
enddo
call toterg(boxn, enn)
arg=-beta*((enn-eno)+p*(vn-vo)
+ -(npart+1)*log(vn/vo)/beta)
if (ranf().gt.exp(arg)) then
    do i=1,npart
        x(i)=x(i)*box/boxn
    enddo
endif
return
end
```

attempts to change  
the volume

total energy old conf.  
determine old volume  
perform random walk in ln V

new box length

rescale center of mass

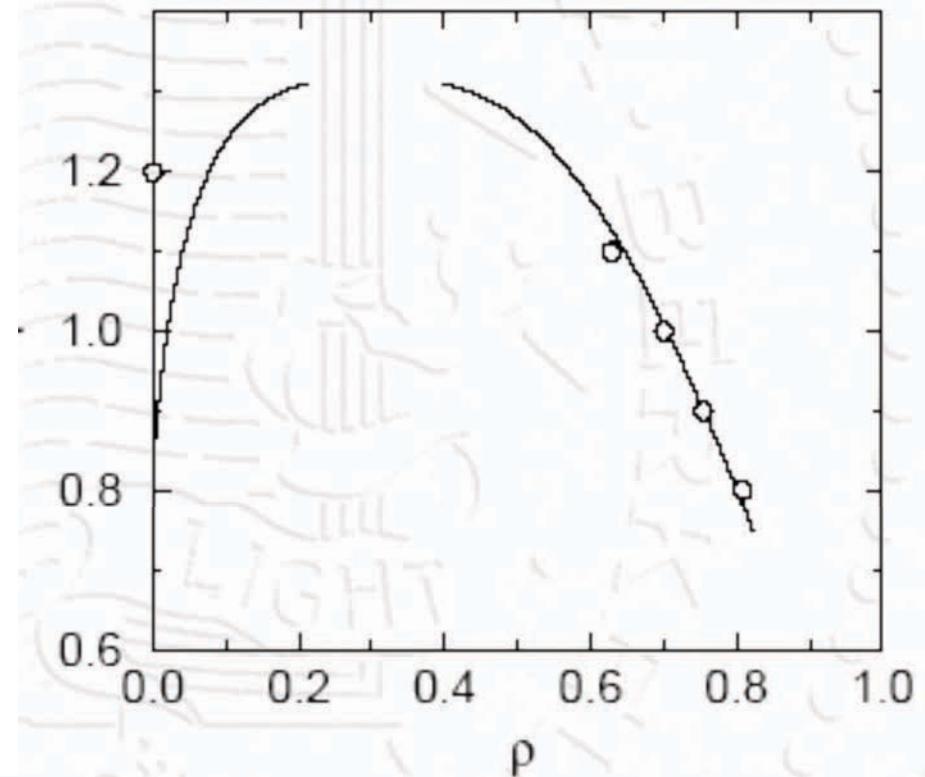
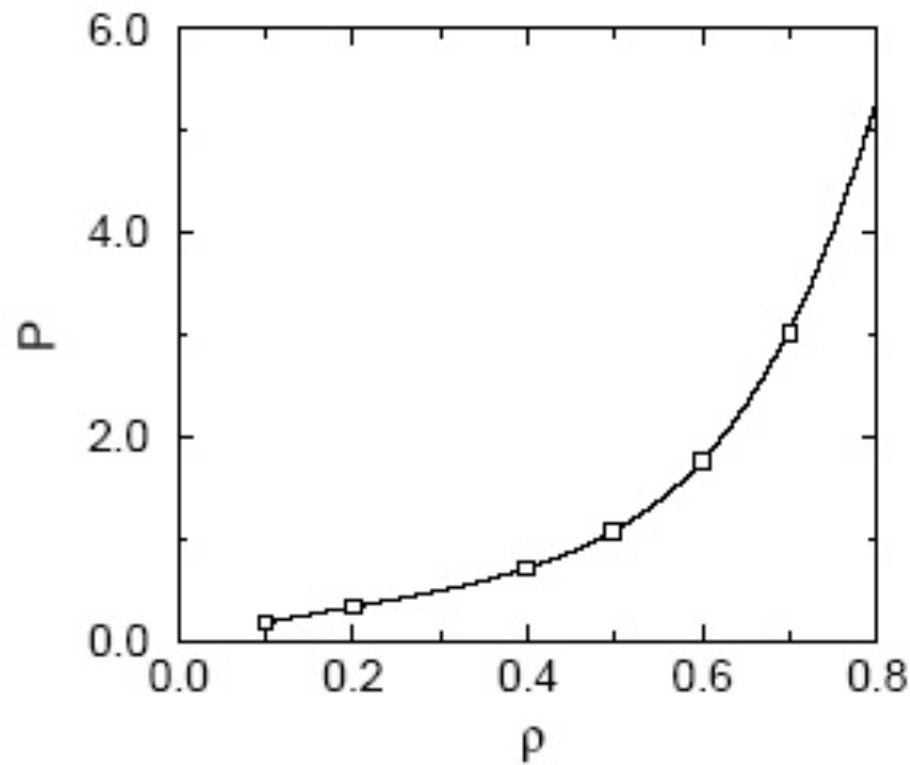
total energy new conf.

appropriate weight function!  
acceptance rule (5.2.3)

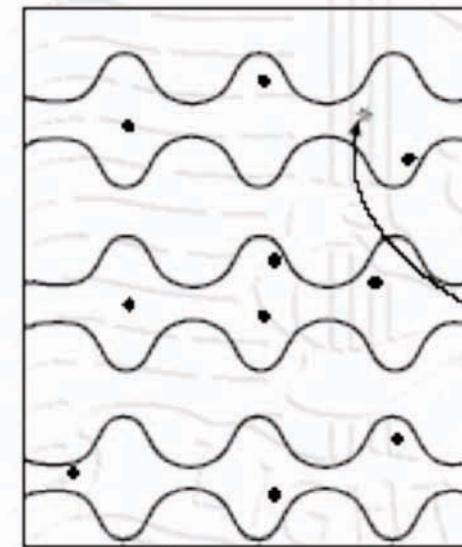
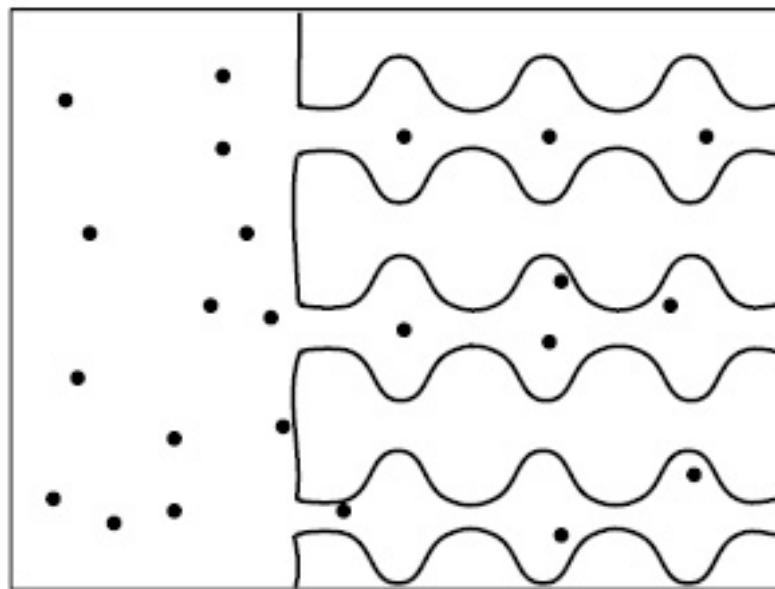
REJECTED

restore the old positions

# NPT simulations

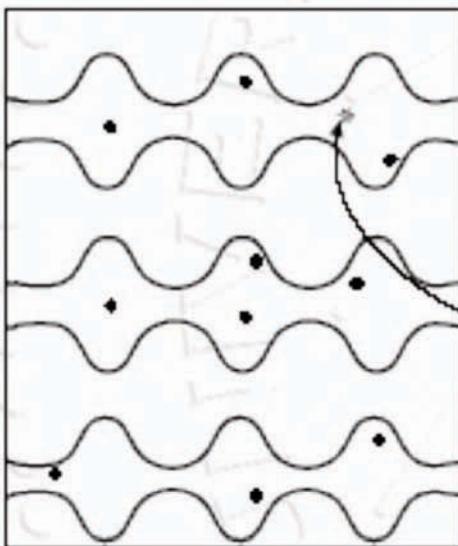


# Grand-canonical ensemble



What are the equilibrium conditions?

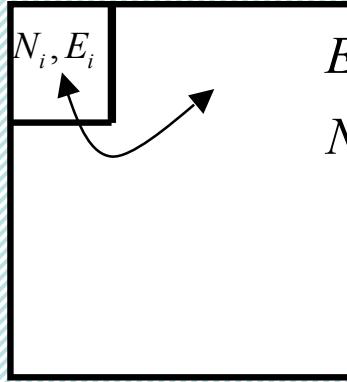
# Grand-canonical ensemble



We impose:

- Temperature
- Chemical potential
- Volume
- But **NOT** pressure

# Grand-canonical simulations: $\mu, V, T$ ensemble



## Thermo recall (5)

First law of thermodynamics

$$dE = TdS - pdV + \sum_i \mu_i dN_i$$

Hence

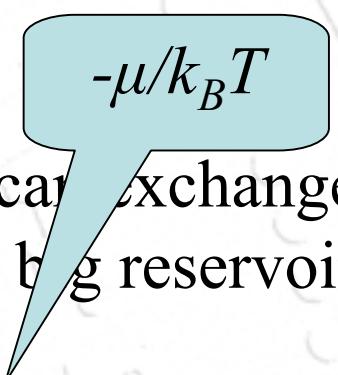
$$\frac{1}{T} = \left( \frac{\partial S}{\partial E} \right)_{V,N}$$

and

$$\left( \frac{\partial S}{\partial N_i} \right)_{T,V} = -\frac{\mu_i}{T}$$

Hence, the probability

$$P(E_i, N_i) = \frac{\beta (E_i - \mu_i N_i)}{\sum_{j,k} \Omega(E - E_j, N - N_k) - \sum_{j,k} \exp[-\beta (E_j - \mu_k N_k)]} \\ \propto \exp[-\beta (E_i - \mu_i N_i)]$$



in that can exchange with a big reservoir

$$-\left( \frac{\partial \ln \Omega}{\partial N} \right)_E N_i + \dots$$

# MuVT Ensemble

Partition function:

$$Q_{\mu VT} = \sum_{N=0}^{N=\infty} \frac{\exp(\beta\mu N) V^N}{\Lambda^{3N} N!} \int d\mathbf{s}^N \exp[-\beta U(\mathbf{s}^N; L)]$$

Probability to find a particular configuration:

$$N_{\mu VT}(N, \mathbf{s}^N) \propto \frac{\exp(\beta\mu N) V^N}{\Lambda}$$

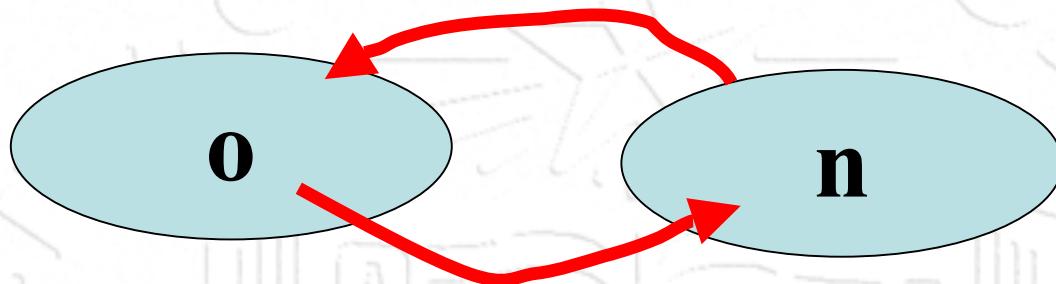
Sample a particular configuration

- Change of the number of particles
- Change of reduced volume

*Detailed balance*

Acceptance rules ??

# Detailed balance



$$K(o \rightarrow n) = K(n \rightarrow o)$$

$$K(o \rightarrow n) = N(o) \times \alpha(o \rightarrow n) \times \text{acc}(o \rightarrow n)$$

$$K(n \rightarrow o) = N(n) \times \alpha(n \rightarrow o) \times \text{acc}(n \rightarrow o)$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n) \times \alpha(n \rightarrow o)}{N(o) \times \alpha(o \rightarrow n)} = \frac{N(n)}{N(o)}$$

# $\mu VT$ -ensemble

$$N_{\mu VT}(N, \mathbf{s}^N) \propto \frac{\exp(\beta \mu N) V^N}{\Lambda^{3N} N!} \exp[-\beta U(\mathbf{s}^N; L)]$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n)}{N(o)}$$

Suppose we change the position of a randomly selected particle

$$\begin{aligned} \frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} &= \frac{\frac{\exp(\beta \mu N) V^N}{\Lambda^{3N} N!} \exp[-\beta U(s_n^N; L)]}{\frac{\exp(\beta \mu N) V^N}{\Lambda^{3N} N!} \exp[-\beta U(s_o^N; L)]} \\ &= \exp\{-\beta [U(n) - U(0)]\} \end{aligned}$$

# $\mu VT$ -ensemble

$$N_{\mu VT}(N, \mathbf{s}^N) \propto \frac{\exp(\beta\mu N)V^N}{\Lambda^{3N} N!} \exp[-\beta U(\mathbf{s}^N; L)]$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n)}{N(o)}$$

Suppose we change the *number of particles* of the system

$$\begin{aligned} \frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} &= \frac{\frac{\exp(\beta\mu(N+1))V^{N+1}}{\Lambda^{3N+3}(N+1)!} \exp[-\beta U(\mathbf{s}^{N+1}; L_n)]}{\frac{\exp(\beta\mu N)V^N}{\Lambda^{3N} N!} \exp[-\beta U(\mathbf{s}^N; L_o)]} \\ &= \frac{\exp(\beta\mu V)}{\Lambda^3(N+1)} \exp[-\beta \Delta U] \end{aligned}$$

## Algorithm 12 (Basic Grand-Canonical Ensemble Simulation)

PROGRAM mc_gc	
do 1cycl=1,ncycl	basic $\mu$ VT ensemble
ran=int(ranf()*(npav+nexc))+1	simulation
if (ran.le.npart) then	perform ncycl MC cycles
call mcmove	displace a particle
else	
call mcexc	exchange a particle
endif	with the reservoir
if (mod(1cycl,nsamp).eq.0)	
+      call sample	sample averages
enddo	
end	

Comments to this algorithm:

1. This algorithm ensures that, after each MC step, detailed balance is obeyed. Per cycle we perform on average npav attempts<sup>6</sup> to displace particles and nexc attempts to exchange particles with the reservoir.
2. Subroutine mcmove attempts to displace a particle (Algorithm 2), subroutine mcexc attempts to exchange a particle with a reservoir (Algorithm 13), and subroutine sample samples quantities every nsamp cycle.

### Algorithm 13 (Attempt to Exchange a Particle with a Reservoir)

```
SUBROUTINE mcexc

  if (ranf().lt.0.5) then
    if (npart.eq.0) return
    o=int(npart*ranf())+1
    call ener(x(o),eno)
    arg=npart*exp(beta*eno)
    +      /(zz*vol)
    if (ranf().lt.arg) then
      x(o)=x(npart)
      npart=npart-1
    endif
  else
    xn=ranf()*box
    call ener(xn,enn)
    arg=zz*vol*exp(-beta*enn)
    +      /(npart+1)
    if (ranf().lt.arg) then
      x(npart+1)=xn
      npart=npart+1
    endif
  endif
  return
end
```

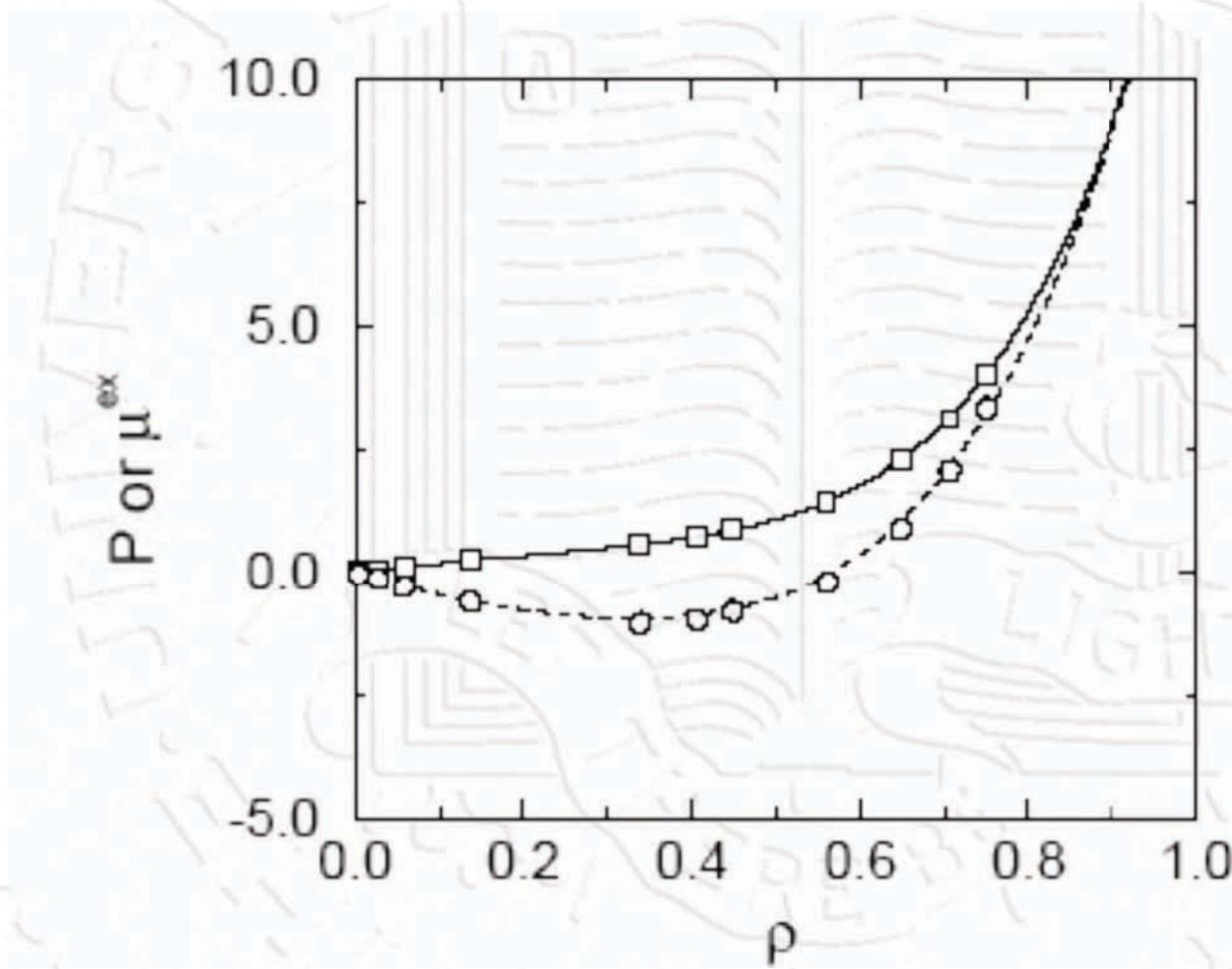
attempt to exchange a particle  
with a reservoir  
decide to remove or add a particle  
test whether there is a particle  
select a particle to be removed  
energy particle o  
acceptance rule (5.6.9)

accepted: remove particle o

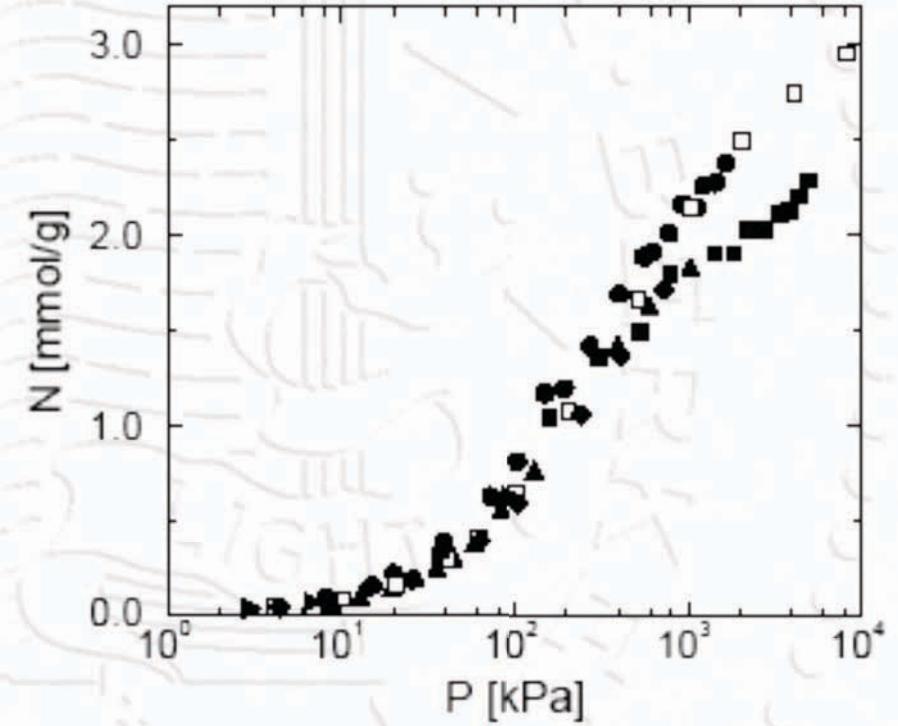
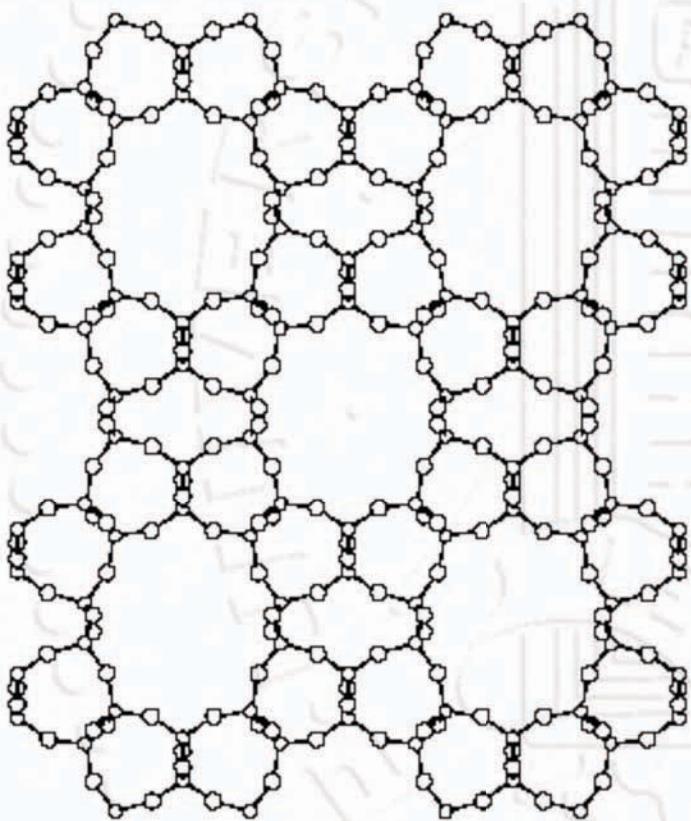
new particle at a random position  
energy new particle  
acceptance rule (5.6.8)

accepted: add new particle

# Application: equation of state of Lennard-Jones

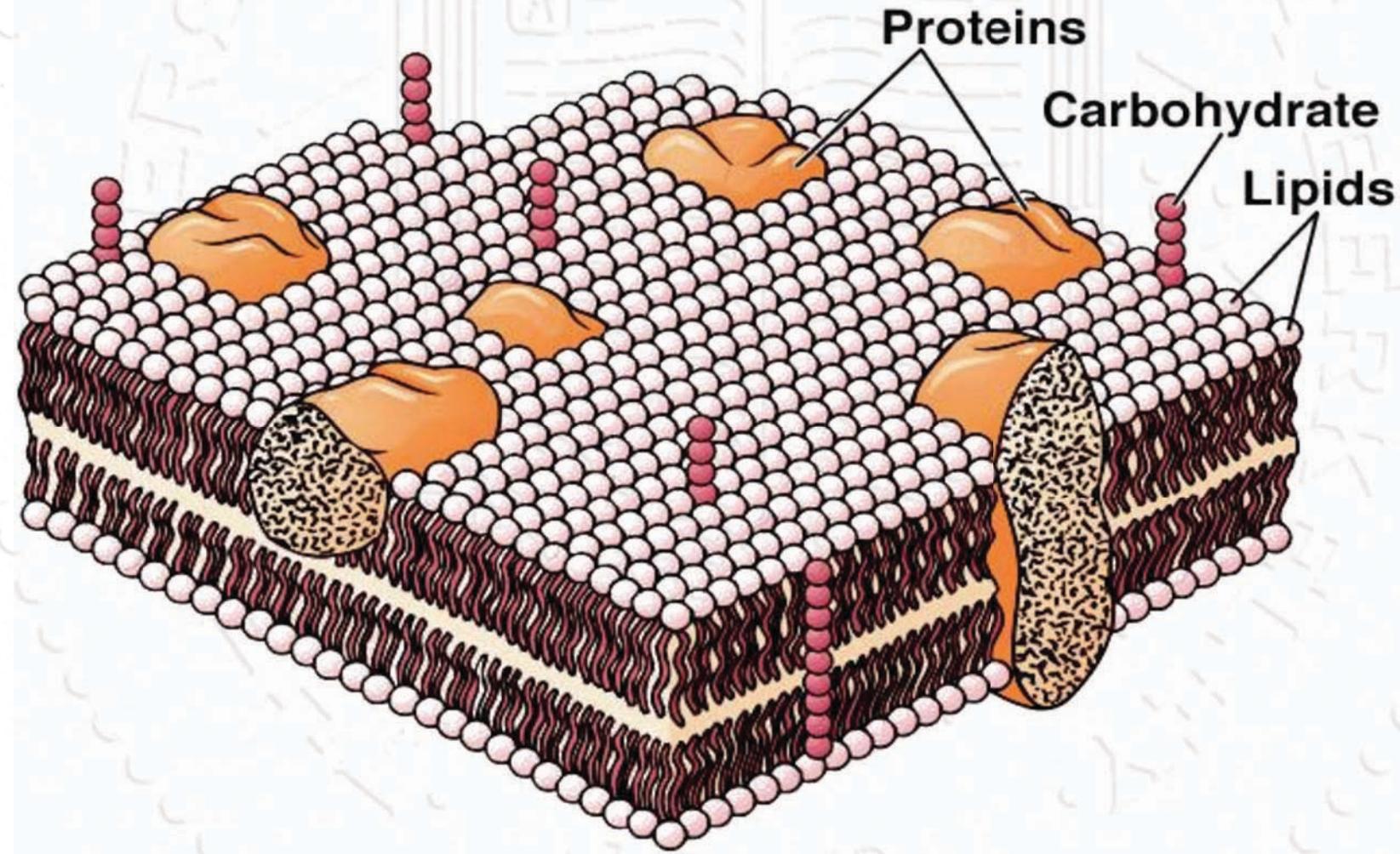


# Application: adsorption in zeolites

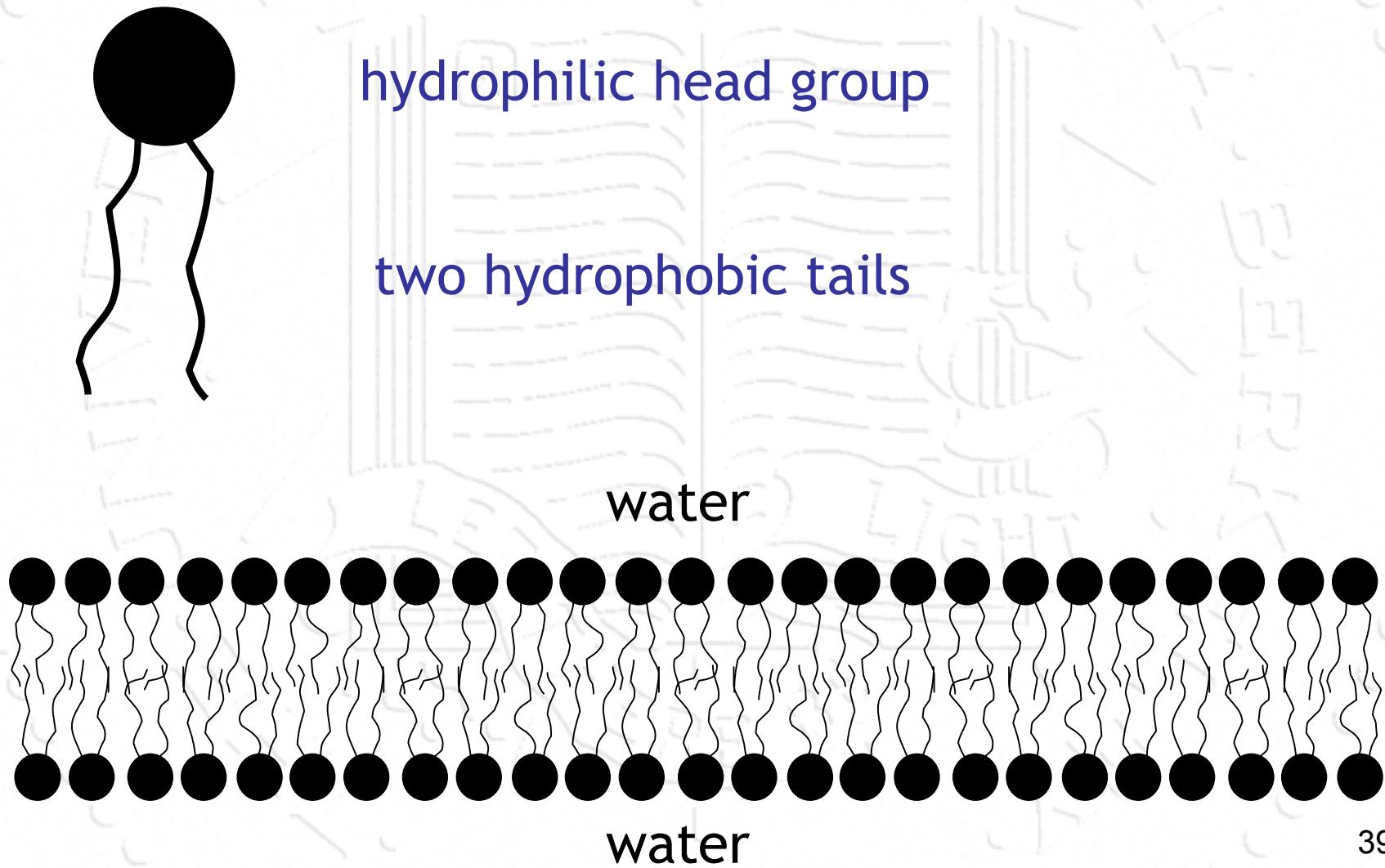


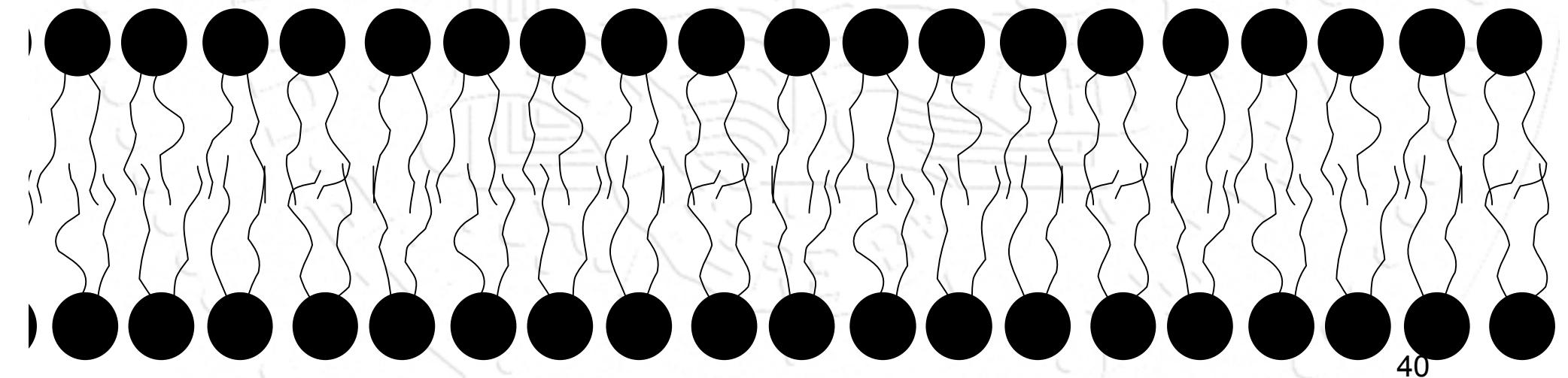
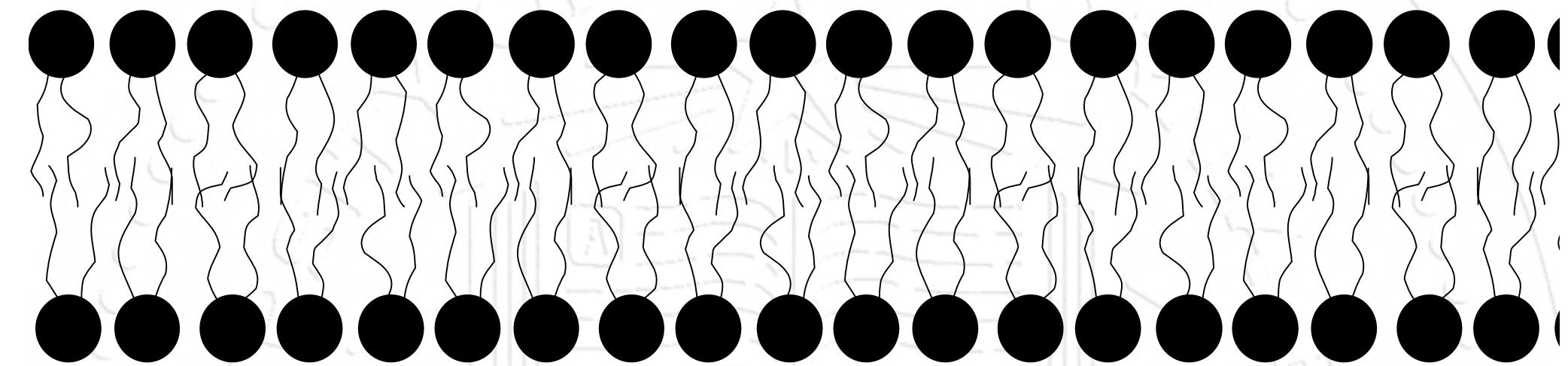
# Exotic ensembles

What to do with a biological membrane?



# Model membrane: Lipid bilayer



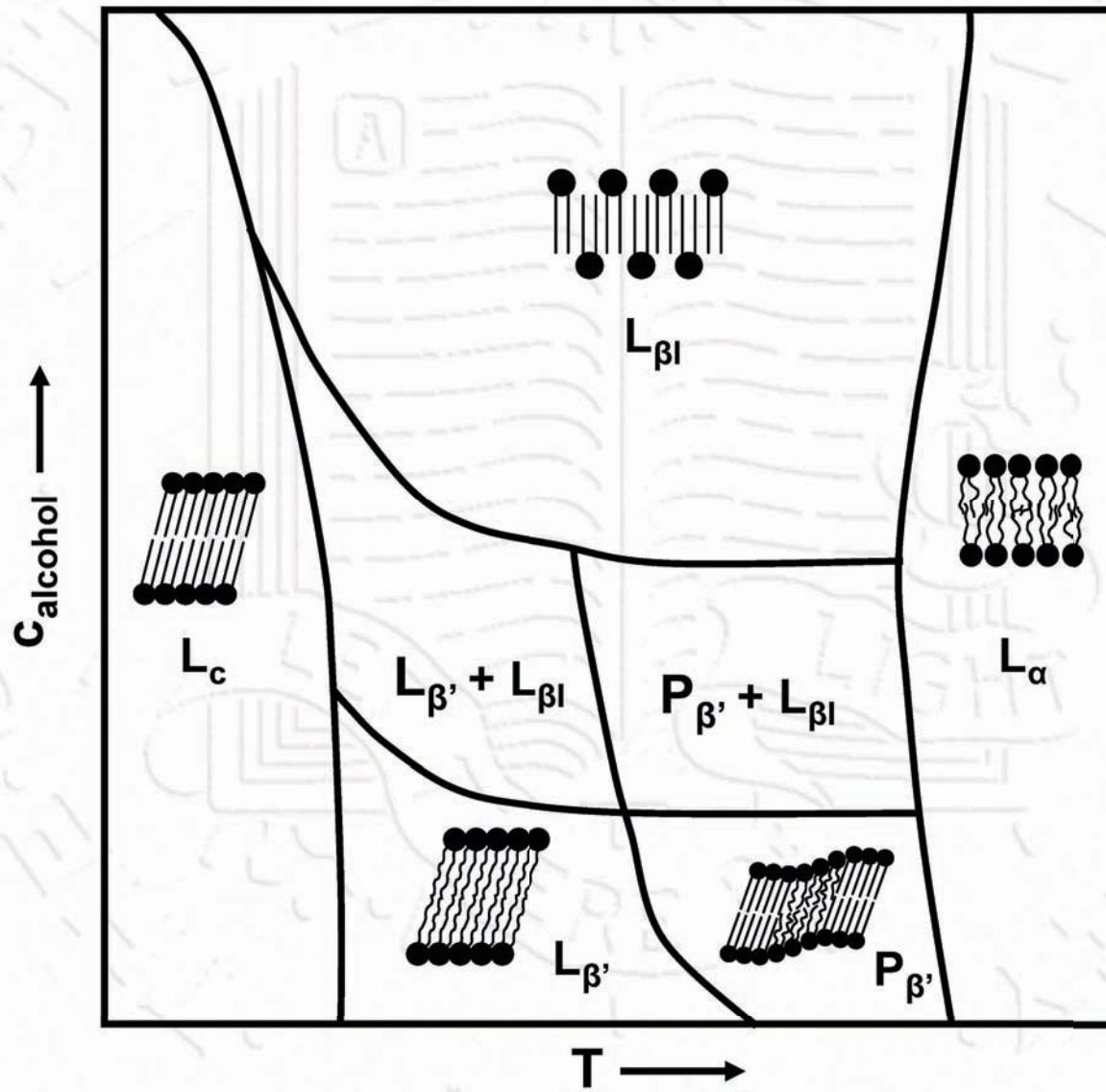


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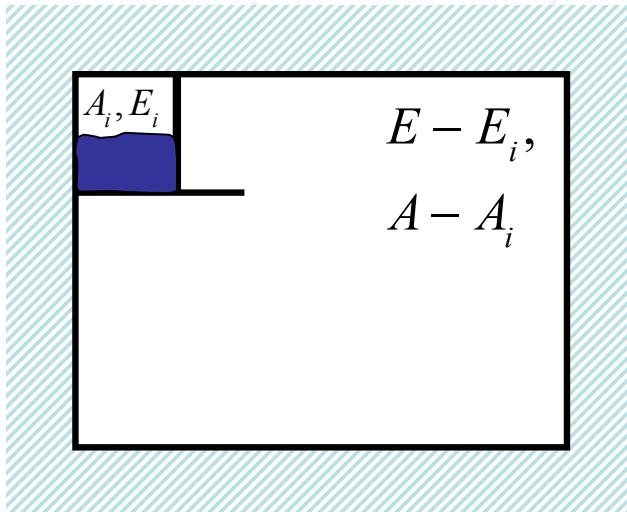
# Questions

- What is the surface tension of this system?
- What is the surface tension of a biological membrane?
- What to do about this?

# Phase diagram: alcohol



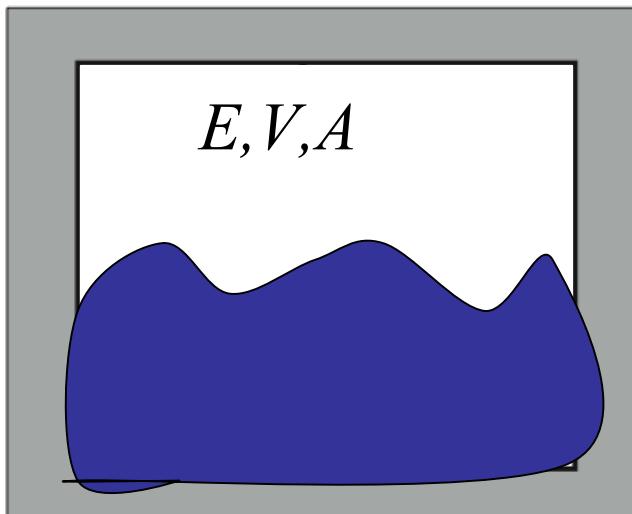
# Constant surface tension simulations: $\gamma, V, T$ ensemble



Consider a small system that can exchange  
and  $1/k_B T$  energy with a reservoir

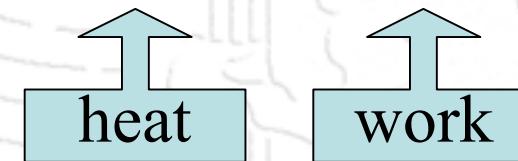
$$\ln \Omega(E - E_i, A - A_i) = \ln \Omega(E, A) - \left( \frac{\partial \ln \Omega}{\partial E} \right)_A E_i - \left( \frac{\partial \ln \Omega}{\partial A} \right)_E A_i + \dots$$

# First law of thermodynamic



Conservation of energy:

$$dE = dq + dw$$



$$dq = TdS$$

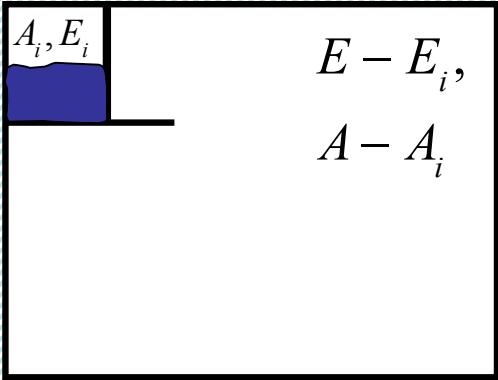
$\gamma$  is the interfacial tension  
of the system

$$dw = -pdV + \gamma dA$$

$$dE = TdS + \gamma dA$$

$$\left( \frac{\partial S}{\partial A} \right)_E = -\frac{\gamma}{T}$$

# Constant surface tension simulations: $\gamma, V, T$ ensemble



$$1/k_B T$$

Consider a small system that can exchange *area* and energy with a big reservoir

$$\ln \Omega(E - E_i, A - A_i) = \ln \Omega(E, A) - \left( \frac{\partial \ln \Omega}{\partial E} \right)_A E_i - \left( \frac{\partial \ln \Omega}{\partial A} \right)_E A_i + \dots$$

$$\left( \frac{\partial \ln \Omega}{\partial A} \right)_N = \left( \frac{\partial S/k_B}{\partial A} \right)_N = -\frac{\gamma}{k_B T}$$

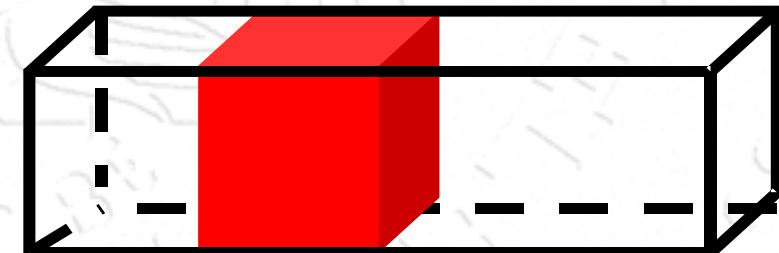
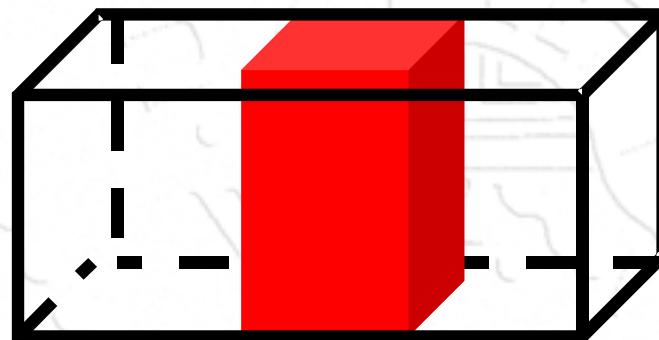
$$\ln \frac{\Omega(E - E_i, A - A_i)}{\Omega(E, A)} = -\frac{E_i}{k_B T} + \frac{\gamma A_i}{k_B T}$$

$$P(E_i, A_i) = \frac{\Omega(E - E_i, A - A_i)}{\sum_{j,k} \Omega(E - E_j, A - A_k)} = \frac{\exp[-\beta(E_i - \gamma A_i)]}{\sum_{j,k} \exp[-\beta(E_j - \gamma A_k)]}$$

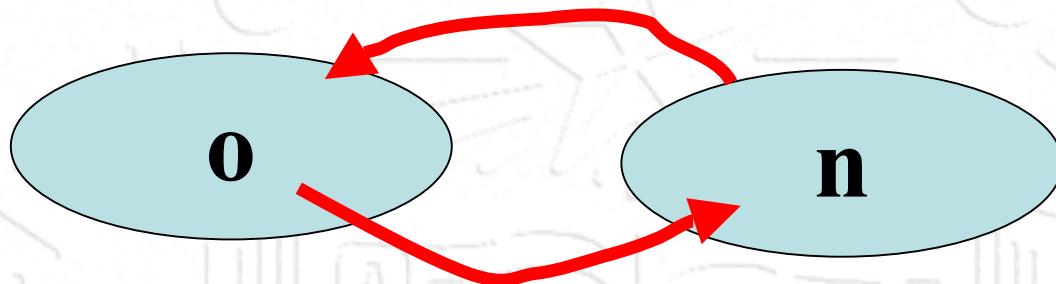
$$\propto \exp[-\beta(E_i - \gamma A_i)]$$

# Simulations at imposed surface tension

- Simulation to a constant surface tension
  - Simulation box: allow the area of the bilayer to change in such a way that the volume is constant.



# Detailed balance



$$K(o \rightarrow n) = K(n \rightarrow o)$$

$$K(o \rightarrow n) = N(o) \times \alpha(o \rightarrow n) \times \text{acc}(o \rightarrow n)$$

$$K(n \rightarrow o) = N(n) \times \alpha(n \rightarrow o) \times \text{acc}(n \rightarrow o)$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n) \times \alpha(n \rightarrow o)}{N(o) \times \alpha(o \rightarrow n)} = \frac{N(n)}{N(o)}$$

# $\gamma VT$ -ensemble

$$N_{\gamma VT}(A, \mathbf{s}^N) \propto \exp[-\beta[U(\mathbf{s}^N; L) - \gamma A]]$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{N(n)}{N(o)}$$

Suppose we change:

$$\left. \begin{array}{l} L_o \rightarrow L_n \\ A_o \rightarrow A_n \end{array} \right\} V_o = V_n$$

$$\frac{\text{acc}(o \rightarrow n)}{\text{acc}(n \rightarrow o)} = \frac{\exp[-\beta[U(s_n^N; L_n) - \gamma A_n]]}{\exp[-\beta[U(s_o^N; L_o) - \gamma A_o]]}$$

$$= \exp\{-\beta[U(n) - U(o)] - \beta\gamma(A_n - A_o)\}$$

# Tensionless state: $\gamma = 0$

$$\gamma(A_o) = -0.3 \pm 0.6$$

$$\gamma(\textcolor{red}{A}_o) = 2.5 \pm 0.3$$

$$\gamma(\textcolor{blue}{A}_o) = 2.9 \pm 0.3$$

